Application of OpenFoam solver SettlingFoam to bedload sediment transport analysis

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Abstract
Sediment transport is an important process for rivers and natural channels. The determination of sediment transport is a very complex process due to the high variability and changing nature of the factors that intervene. As a contribution to the description of this kind of phenomenon and to highlight the problems, the needs and potentials of the numerical approaches, OpenFOAM solver settlingFoam is used to simulate sediment transport in a rectangular channel. The model used constitutes a simplification of a complex procedure based on the application of a single parameter (alpha) to determine the fluid-sediment mixture features. High variability was found between the results from different alpha values. Nevertheless, there is a lack of information to determine the appropriate value of this parameter. However, even though the procedure applied and the results obtained have to be taken as a reference, this study provides valuable criteria for future research of this complex topic.

Keywords: numerical model; sediment transport; mixture theory; turbulence model.

1. Introduction
Sediment transport has considerable impact on river processes. It defines river morphology [1] and also has influence on water quality [2]. In North America the water pollution by sediments has an estimated cost of $16 billion per year [3]. Even though sediment transport of fine material $1.56 < d_{50}(\text{mm}) < 28.6$ has been studied in detail by [4-7], these studies don’t apply properly for coarser size sediments. Additionally, the slope plays an important role. The studies developed consider mainly mild slopes [8].

The study of sediment transport in steeper channels with coarse material is a complex process. Continuously changing driving forces, basin sediment production, and river bed conditions such as high gradients and large roughness elements result in high uncertainty in the quantification of sediment transport rates [1,9,10]. The uncertainty reported...
can reach some orders of magnitude [9,11]. Some equations have been proposed to account for bedload, movement thresholds, and channel roughness of steep channels with coarse material. Nevertheless, it is concluded that there are more formulae than consistent data to verify them. Besides, no formula is proved to achieve consistent results, and no universal relation has been defined between bedload discharge and hydraulic conditions [12-14]. The essence, nature, and physics of sediment transport under these conditions (coarse material and steep channels) make its quantification a difficult process that still needs further investigation to achieve reliable results.

As an initial approach to achieve reliable tools to characterize sediment transport processes, in the present work, a sediment transport numerical model is applied to a study case. The case corresponds to a rectangular steel-glass channel with sediment entrance just at the inlet cross section. Thus, the settling features and transport velocity of a rectangular channel with water and sediment are determined. The main idea of developing the present application is to face the challenges, requirements, and potentialities (for a simple case) of this kind of models in order to project them to a simulation of more complex cases like natural rivers with steep slopes and coarse sediment.

2. Methods

A numerical model that replicates the hydrodynamics of a two-phase (sediment and water) flow is developed to determine the distribution of the two phases along the domain, the sediment transport velocity, and the general flow variables pressure and velocity. The numerical analysis is performed with Open Filed Operation and Manipulation (OpenFOAM), an open source computational fluid dynamics (CFD) software package. It includes built-in applications, but can be used also to create new ones. The applications can be classified as solvers, used to find solutions to specific equations, and as utilities that can be seen as tools for data analysis and manipulation, generally results from the solvers (OpenVFOAM 2014). This software is used to solve the Navier-Stokes equations, the governing equations for this problem.

For modeling sediment transport OpenFOAM has a solver called settlingFoam. This model considers the mixture formed by water and sediment as a single phase instead of two separate phases. Considering each phase separately, a proper detail of the flow processes of each individual phase can be obtained. However, in the area where the two phases interact, there are difficulties in simulating the terms of the momentum transfer between the two phases.

The main purpose of this solver is to determine the relative movement between the two phases. The density and pressure of the mixture are respectively defined with the following expressions:

\[ \rho_m = \alpha_1 \rho_1 + \alpha_2 \rho_2, \]  
\[ P_m = \alpha_1 P_1 + \alpha_2 P_2, \]

The center velocity of the mixture volume is defined as follows:

\[ v_m = \frac{\alpha_1 \rho_1 v_1 + \alpha_2 \rho_2 v_2}{\rho_m}, \]

The governing equations for the mixture flow, including the previous relations, are defined with the next expressions: Mixture Continuity Equation,

\[ \frac{\partial \rho_m}{\partial t} + \nabla \cdot (\rho_m u_m) = 0, \]

Mixture Momentum Equation,

\[ \frac{\partial \rho_m u_m}{\partial t} + \nabla \cdot (\rho_m u_m u_m) = -\nabla P_m + [\tau + \tau_t] - \nabla \left( \frac{\alpha_d \rho_d}{1-\alpha_d} \rho_m \gamma_{dj} v_{dj} v_{dj} \right) + \rho_m g + M_m, \]

Drift Equation,

\[ \frac{\partial \alpha_d}{\partial t} + \nabla \cdot (\alpha_d v_m) = -\nabla \left( \frac{\alpha_d \nu_d}{\rho_m} \right) + \nabla \cdot \Gamma \nabla \alpha_d, \]

Where, \( \alpha_d \) represents the dispersed phase volume fraction, \( P_m \), \( \rho_m \), and \( u_m \) account for the average flow properties and \( \nu_d \) for the dispersion phase drift velocity. Finally, \( \Gamma \) is the diffusion coefficient composed by the molecular and turbulent viscosity.

Since the flow features of natural steep channels correspond to turbulent flow, the direct solution of the governing equations is not possible at a reasonable computational cost and simulation time. The resolution required by a DNS of isotropic turbulence that incorporates the viscous dissipation can be projected as four times the Kolmogorov length scale. Even for the smallest length scale the necessary mesh points is proportional to \( Re^{3/4} \). In open channel flow the resolution requirement is also dependent on the Reynolds number \( Re \). It can be estimated as \( N_{xyz} = 2 \times 10^6 (Re/300)^{2/7} \). Moreover, to solve the smallest eddies adequately the time step does not have to carry a fluid particle further than one cell [15]. Consequently, time step has to be decreased if cell size is decreased. Even for simple laminar cases, direct numerical simulations (DNS) have high costs [16]. A DNS is the most accurate, but even for low Reynolds number cases it has a high computational cost. It is impossible with the available tools to obtain a DNS for a complex geometry. Therefore, an alternative that balances accuracy and computational cost must be used [17].

2.1. Turbulence approach

To solve the Reynolds averaged Navier-Stokes equation, (RANS) two general categories can be applied. The first category, known as the eddy viscosity models, express the components of the Reynolds stress tensor as functions of the gradients of the mean velocity. These models can be classified in turn in isotropic (linear) or non-isotropic (non-linear), depending on which constitutive turbulence law they use. Additionally, depending on the procedure employed to determine the eddy viscosity, these models can be algebraic or differential. The second category depends on Second Moment Closure (SMC) models or Reynolds-Stress Transport (RST) models. For these types of models, the modelled solutions of RST equations are the components of the Reynolds stresses required to close the RANS [18].
2.2. Isotropic eddy viscosity models

The eddy-viscosity concept of Boussinesq is the base of most of the turbulence models. It assumes that the turbulence shear stresses are proportional to the main velocity gradient. Eddy-viscosity models express eddy viscosity \( \nu_t \) as the product of a turbulence length scale, \( l_t \), and a turbulence velocity scale, \( u_t \).

\[
\nu_t = l_t u_t, \quad (7)
\]

As a function of the way in which these scales are calculated, the models can be divided in three kinds: zero-equation or algebraic eddy-viscosity models, one-equation models, and two-equation models.

2.3. Two-equation models

These models use one PDE (partial differential equation) for the length scale and one PDE for the velocity scale [18]. These models mostly use the same transport equation for the Turbulence Kinetic Energy (TKE) to calculate a local turbulence velocity scale \( (u_t \approx k^{1/2}) \) [15]. The most common two-equation models are the \( k-c \) model and the \( k-\omega \) models.

2.4. The \( k-c \) model

This model utilizes an equation for the turbulent energy dissipation \( \epsilon \sim k^{3/2}/L \), instead of the direct determination of the length scales, \( L \), together with the kinetic energy \( k \) equation [17].

The semi-empirical \( k \)-equation and \( \epsilon \)-equation are expressed as follows:

For the transport of the kinetic energy \( k \):

\[
\frac{\partial k}{\partial t} + \nabla \cdot (k \mathbf{u}) = \frac{\partial}{\partial x_i} \left( \nu_t \frac{\partial k}{\partial x_i} \right) + \nu \left( \frac{\partial u_i}{\partial x_i} + \frac{\partial u_j}{\partial x_j} \right) \frac{\partial u_i}{\partial x_j} - \epsilon, \quad (8)
\]

The terms in equation (8), from left to right, correspond to rate of change, convective transport, diffusive transport, production by shear, and dissipation.

For the transport of the dissipation rate \( \epsilon \):

\[
\frac{\partial \epsilon}{\partial t} + \nabla \cdot \left( \epsilon \mathbf{u} \right) = \frac{\partial}{\partial x_i} \left( \nu_t \frac{\partial \epsilon}{\partial x_i} \right) + \frac{C_1 \epsilon}{k} \nu_t \mathbf{u}^{2} - C_2 \epsilon \frac{\epsilon^2}{k}, \quad (9)
\]

The terms in equation (9), from left to right, correspond to rate of change, convective transport, diffusive transport, generation-destruction,

\[
P = \nu_t \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \frac{\partial u_i}{\partial x_j}, \quad (10)
\]

where, \( P \) is the generation term of the turbulent kinetic energy, and \( C_{1\epsilon}, C_{2\epsilon}, C_\sigma, C_\mu \) are empirical constants.

Turbulent eddy viscosity is then calculated when \( k \) and \( c \) have been solved with the Prandtl-Kolmogorov expression [17].

\[
\nu_t = C_\mu \left( \frac{k^2}{\epsilon} \right), \quad (11)
\]

2.5. Domain

The domain chosen for this study corresponds to a rectangular channel 30 cm wide by 45 cm high by 6 m long. As a prismatic small dimensions channel, the flow will be considered just in two dimensions (height and length). The two phases interaction simulated in settlingfoam are the fluid and sediment phase, established as the dispersed phase.

2.6. Boundary conditions

For the flow in a rectangular channel with the dimensions presented above, the boundary conditions include: two walls (upper and lower), inlet, and outlet. One velocity value was given for the inlet and walls. For the lower wall the non-slip condition (zero velocity) is set. The upper wall was given a slip condition. Outlet velocity is calculated. Furthermore, zero differential pressure is assigned to the outlet. For the walls and inlet, pressure is calculated.

Velocity and pressure were established based on laboratory conditions; \( k \) and \( \epsilon \) were determined from the theory developed for turbulence models [19]. Here, the main relations used to determine the boundary conditions are presented.

\[
k = \frac{3}{2} (u \cdot I)^2, \quad (12)
\]

\[
I = 0.16 R e_o^{-1/8}, \quad (13)
\]

\[
\epsilon = C_\mu \frac{k^{3/2}}{L}, \quad (14)
\]

\[
L = 0.038 R, \quad (15)
\]

where, \( u \) represents the main channel velocity, \( I \) is the turbulence intensity, \( R \) is the jet Reynolds number, \( L \) represents the length scale, and \( R \) is the hydraulic radius.

Three sediment volume fractions are simulated. There is not any guide to set the alpha \( (\alpha_d) \) volume as a function of the sediment conditions. Therefore, values of alpha corresponding to 1%, 0.1% and 0.01% of sediment are simulated to determine the effect of this parameter in the final solution.

2.7. Mesh

The domain is divided in uniform discrete cells of 0.01x0.01m, giving a total of 27,000 cells in the entire domain.

2.8. Schemes

The numerical method used by OpenFOAM is the finite volume method. For the time operator the Euler scheme is used. The Gauss linear scheme is used for the gradient and divergence operators. For the Laplacian operator, the Gauss linear corrected scheme is applied. Additionally, the interpolation scheme is set to linear. All of the schemes used have second-order accuracy [20]. Therefore, the simulations are considered second-order accurate. To verify solution’s convergence two parameters are analyzed. First, the residuals for the pressure, velocity and alpha equations are verified to drop to low values. The residuals are obtained from the absolute difference of the solution between the
\(n^{th}\) and \((n-1)^{th}\). Additionally, change of the solution (alpha, velocity, and pressure) is tracked throughout the entire simulation to ratify that a steady-state solution has been achieved. All the simulations comprised 100,000 iterations. The final time corresponds to 2000s with a variable time step (between 0.01s).

3. Results

As stated previously, some scenarios are considered to determine the influence of the parameter alpha and also to account for possible circumstances that may arise in the field. Summarizing, the simulations are performed with three different values of alpha: 0.01, 0.001, and 0.0001.

3.1. Residuals

The convergence criteria are verified with the residuals from the pressure, velocity and alpha equation. In Fig. 1 (a), (b) and (c) the residuals are presented for alpha = 0.01, 0.001, and 0.0001 respectively. As can be seen in the figures, the highest residuals correspond to pressure in all three cases. Comparing the different alpha values, the highest residuals correspond to alpha of 0.01.

![Residuals (alpha = 0.01)](image)

![Residuals (alpha = 0.001)](image)

Smaller residuals are obtained with small alpha values. This might indicate that small alpha values produce more stable solutions. For pressure, the residuals decrease two orders of magnitude when alpha decreases one order of magnitude. Similarly, residuals decrease two orders of magnitude when alpha decreases two orders of magnitude. For velocity, the residuals practically maintain their value for all alpha values simulated. A slight diminution is reported for the two smaller alpha values. However, considering the low value of velocity residuals this reduction is considered as non-significant. Alpha equations residuals are the lowest reported values. For the highest alpha value the residuals ranges from \(10^{-8}\) to \(10^{-10}\). For the two lower alpha values, residuals fall below \(10^{-10}\). As observed alpha value adopted has considerable impact on the convergence of the solution.

3.2. Monitor point

The change in pressure, velocity, and alpha at a selected location (point: 3, 0.15) was monitored over the course of the simulation.

The results presented in Fig. 2 correspond to the parameters analyzed as follows. Fig. 2 (a) presents the alpha variation in the case of \(a_d = 0.01\). Fig. 2 (b) details pressure variation for \(a_d = 0.001\), Finally, Fig. 2 (c) shows the variation of the velocity for \(a_d = 0.0001\).

![Residuals (alpha = 0.0001)](image)

Considering Fig. 2, the following can be reported. The pressure solution for \(a_d = 0.01\) does not reach a constant value. However, the variation registered is small. This is in accordance with the small values reported for the residuals. In the case of alpha (\(a_d = 0.001\)), the constant values is reached around the time 1200s. For velocity and \(a_d = 0.0001\), the solution remains constant after the time 1500s. For all simulations (three alpha values), similar characteristics are obtained. In Fig. 2, a representative case of each parameter is presented.
3.3. Alpha

The alpha variation around the whole domain is presented in Fig. 3 for all three values of alpha considered. As can be seen in the figure, the data scale for (a) and (b) are the same. For (c) the scale is reduced to adjust the figure to the values of that case. Due to the high value of alpha in (a) the dispersed phase (sediment phase) is filling almost the entire domain. Being as the inflow of sediment is permanent during the simulation and the high sediment concentration, in this case the sediment phase occupies a high percentage of the channel.

In Fig. 3 (b), ($\alpha_d = 0.001$) it can be seen that sediment has settled almost entirely approximately the 75% of the domain. The first quarter of the domain contains a higher amount of sediment. Nevertheless, this amount is smaller than the one settled in the channel bottom. For Fig. 3 (c) the reported results are similar to those obtained in Fig. 3 (b); the only difference is the absolute value of alpha.

3.4. Drift velocity

As can be observed in Fig. 4 (a), (b), and (c), the drift velocity shows exact correspondence to the alpha values. High velocity values correspond to small alpha values and small velocities match with high alpha values. Namely, the sediment phase will be dragged by smaller velocities than the fluid phase.
3.5.  Velocity and velocity vectors

As presented in Fig. 5(a), (b), and (c), flow velocity presents a different pattern for \( \alpha_d = 0.001 \). For high and low alpha the flow configuration is similar. The flow domain, for intermediate alpha, presents recirculation zones following the pattern defined for alpha changes replicating what it is observed with drift velocity.

3.6.  Vertical velocity profile

Vertical velocity profiles were obtained at the middle of the domain. The results are presented in Fig. 6. As can be observed, different velocity profiles were obtained with the different alpha values. The maximum flow velocity is reported for \( \alpha_d = 0.001 \) with a value of 0.044 m/s. The dissimilar behavior observed in the previous figures is also registered for the velocity profiles for each value of alpha. For \( \alpha_d = 0.01 \), a severe increase in the velocity is presented in the top of the domain. This can be caused for the change between sediment phase and boundary condition in a small distance (one cell).

4. Conclusions

A numerical model was set to analyze sediment transport processes in a rectangular channel. The numerical model is based on mixtures theory. It constitutes a simple approach to a very complex problem. Well tested and strictly proven procedures like the discrete numerical solution of the Navier-Stokes equations and turbulence models were used in the present simulations. However, a simple method, that just considers a single parameter (alpha) to characterize the mixture, is applied to intend to replicate the natural process. As can be seen in the results, a considerable variability is found with the variation of alpha. Parameters such as flow and drift velocity report a dependence on the alpha value. Specifically, as alpha decreases the channel transport capacity appears to increase (drift velocity increases). Flow velocity presents a different behavior for the medium alpha used. With slight differences, the highest and lowest alphas show similar trends. Additionally, as has been pointed alpha has influence even in the stability and convergence of the equation’s solution. Conversely, no hint is available for the correct determination of this parameter. To obtain accurate results, a calibration and validation of the final alpha value must be performed. Thereby, a methodology can be established to define the correct alpha value.

This work and the application of settlingFoam can be considered as a first simple approach to the numerical simulation of sediment transport processes. The methodology applied here can be taken as the very first step to achieve a more realistic simulation. The simplicity found in the procedure can lead to the reduction in applicability of the method just for simple cases and the results as a reference of the real values. To set a more realistic numerical model an extensive investigation must be accomplished for both field conditions and model-required parameters.
References


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