

## THE PLATEAU PROBLEM FOR THE PRESCRIBED MEAN CURVATURE EQUATION

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### §1. INTRODUCTION

Given a Jordan curve  $\Gamma$  in  $\mathbb{R}^3$  and  $H : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  a continuous and bounded function, we consider the Plateau problem in the unit disc  $B = \{(u, v) \in \mathbb{R}^2 ; u^2 + v^2 < 1\}$ , i.e we look for a vector function  $X : \bar{B} \rightarrow \mathbb{R}^3$  which satisfies the following system of nonlinear differential equations

$$\begin{cases} (1) \Delta X = 2H(X)X_u \wedge X_v & \text{in } B \\ (2) |X_u|^2 - |X_v|^2 = 0 = X_u \cdot X_v & \text{in } B \\ (3) X|_{\partial B} : \partial B \rightarrow \Gamma & \text{is a parametrization of } \Gamma \end{cases} \quad (P)$$

where  $X_u = \frac{\partial X}{\partial u}$ ,  $X_v = \frac{\partial X}{\partial v}$  and  $\wedge$  denotes the exterior product in  $\mathbb{R}^3$ .

As in [5] we define the following subset of the Sobolev space  $H^1(B, \mathbb{R}^3)$ :

$$C(\Gamma) = \{X \in H^1(B, \mathbb{R}^3) : X|_{\partial B} \in C^0(\partial B, \mathbb{R}^3)\}$$

is a weakly monotone parametrization of  $\Gamma$  } .

We call  $X \in C(\Gamma)$  a weak solution of (P) if for every  $\varphi \in C_0^1(B, \mathbb{R}^3)$

$$\int_B \nabla X \cdot \nabla \varphi + 2H(X)X_u \wedge X_v \cdot \varphi = 0 \quad (4)$$

and if  $X$  satisfies (2) in  $B$ .

We will consider  $H$  prescribed and obtain weak solutions of (P) as critical points of the functional

$$D_H(X) = D(X) + 2V(X) ,$$

with

$$D(X) = \frac{1}{2} \int_B |\nabla X|^2$$

being the Dirichlet integral and

$$V(X) = \frac{1}{3} \int_B Q(X) \cdot X_u \wedge X_v$$

the Hildebrandt volume, where for  $\xi = (\xi_1, \xi_2, \xi_3)$  in  $\mathbb{R}^3$ , the associated function  $Q$  to  $H$  is

$$Q(\xi) = \left( \int_0^{\xi_1} H(s, \xi_2, \xi_3) ds, \int_0^{\xi_2} H(\xi_1, s, \xi_3) ds, \int_0^{\xi_3} H(\xi_1, \xi_2, s) ds \right),$$

which satisfies  $\operatorname{div} Q = 3H$  [3].

**Notations.** We denote by  $W^{m,p}(B, \mathbb{R}^3)$  the usual Sobolev spaces [1] and  $H^m(B, \mathbb{R}^3) = W^{m,2}(B, \mathbb{R}^3)$ . For  $X \in H^1(B, \mathbb{R}^3)$ ,

$$\|X\|_{L^2(\partial B, \mathbb{R}^3)} = \left( \int_{\partial B} |\operatorname{Tr} X|^2 \right)^{1/2},$$

where  $\operatorname{Tr} : H^1(B, \mathbb{R}^3) \rightarrow L^2(\partial B, \mathbb{R}^3)$  is the usual trace operator [1] and for  $Y \in L^\infty(U, \mathbb{R}^n)$ , we denote

$$\|Y\|_\infty = \sup_{w \in U} |Y(w)|.$$

For example,

$$\|H\|_\infty = \sup_{\xi \in \mathbb{R}^3} |H(\xi)|,$$

$$\|Q\|_\infty = \sup_{\xi \in \mathbb{R}^3} |Q(\xi)|,$$

and

$$\|H(X)\|_\infty = \sup_{\xi \in B} |H(X(w))|,$$

$$\|Q(X)\|_\infty = \sup_{\xi \in B} |Q(X(w))|.$$

Concerning  $D_H$  (resp.  $V$ ) we set

$$dD_H(X)(\varphi) = \lim_{t \rightarrow 0} \left[ \frac{D_H(X + t\varphi) - D_H(X)}{t} \right],$$

whenever this limit exists (resp.  $dV(X)(\varphi)$ ).

If  $X \in H^1(B, \mathbb{R}^3)$ ,  $\varphi \in C_0^1(B, \mathbb{R}^3)$  then  $dD_H(X)(\varphi)$  exists and is equal to the first member of (4) [cf. 4, Lemma 2].

Finally,  $(n, \sigma)$  denotes polar coordinates in  $\mathbb{R}^3$ , in particular  $\frac{\partial}{\partial n}$  is the normal derivative and  $\frac{\partial}{\partial \sigma}$  the tangential derivative on  $\partial B$ .

§2. MINIMA IN SUBSETS OF  $H^1(B, \mathbb{R}^3)$

We find weak solutions of (P). A first solution is a local minimum of  $D_H$  in a convenient subset of  $H^1(B, \mathbb{R}^3)$  when  $Q$  is in a specific convex subset of  $L^\infty$  and  $\Gamma$  is a rectifiable Jordan curve in  $\mathbb{R}^3$ . Other solutions are either a local minimum of  $D_H$  with respect to the  $W^{2,\infty}(B, \mathbb{R}^3)$ -topology or a sequence of minima of  $D_H$  in convenient closed convex subsets of  $H^m(B, \mathbb{R}^3)$  associated to  $H$  and  $\Gamma$ .

As in [5] we define

$$C^*(\Gamma) = \{X \in C(\Gamma) : X(P_j) = Q_j, j = 1, 2, 3\},$$

where  $P_j = e^{i\varphi_j}$ ,  $0 \leq \varphi_1 < \varphi_2 < \varphi_3 < 2\pi$ , and  $Q_j, j = 1, 2, 3$  an oriented triple on  $\Gamma$ .

It is known that  $C^*(\Gamma)$  is a weakly closed subset of  $H^1(B, \mathbb{R}^3)$  but  $C(\Gamma)$  is not and that for any rectifiable Jordan curve  $\Gamma \subset \mathbb{R}^3$ ,  $C(\Gamma) \neq \emptyset$  [5].

Finally, we know that if  $X \in H^1(B, \mathbb{R}^3)$  is a critical point of  $D$  in the following sense: for any differentiable family of diffeomorphisms  $g_\epsilon : B \rightarrow B_\epsilon$ , with  $g_0 = \text{id}$  there holds

$$\left. \frac{d}{d\epsilon} D(X \circ g_\epsilon^{-1}, B_\epsilon) \right|_{\epsilon=0} = 0,$$

then  $X$  satisfies (2) in (P), i.e. the coordinates  $(u, v)$  are isothermal, and any minimizer  $X$  of  $D_H$  in  $C(\Gamma)$  will be a critical point of  $D$  in this sense [5].

We give proofs based on the technical lemmas in section 3.

**Theorem 1.** *Let  $H : \mathbb{R}^3 \rightarrow \mathbb{R}$  be continuous and bounded. If the function  $Q \in C^1(\mathbb{R}^3, \mathbb{R}^3)$  associated to  $H$  satisfies  $\|Q\|_\infty < \frac{3}{2}$  and  $\frac{\partial Q_i}{\partial \xi_j} \in L^\infty(\mathbb{R}^3)$  for  $i \neq j$ , then given a Jordan curve  $\Gamma$  in  $\mathbb{R}^3$  such that  $C(\Gamma) \neq \emptyset$ , the functional  $D_H$  has a minimum  $\underline{X}$  in  $C^*(\Gamma)$  and  $\underline{X}$  is a weak solution of (P).*

*Proof.* From

$$|\zeta \cdot \eta \wedge \xi| \leq \frac{1}{2} |\zeta| (|\eta|^2 + |\xi|^2),$$

for vectors in  $\mathbb{R}^3$ , we have for  $X \in H^1(B, \mathbb{R}^3)$  that

$$\begin{aligned} |D_H(X)| &\leq D(X) + \frac{2}{3} \int_B |Q(X) \cdot X_u \wedge X_v| \\ &\leq D(X) + \frac{2}{3} \|Q\|_\infty D(X) \\ &< 2D(X), \end{aligned}$$

so  $D_H$  is finite in  $H^1(B, \mathbb{R}^3)$ .

From Lemma 2 [4],  $D_H$  is weakly lower semicontinuous in  $H^1(B, \mathbb{R}^3)$ , and coercive in  $C(\Gamma)$ , because for  $X \in C(\Gamma)$ , we have the Sobolev inequality, which is valid for  $X \in H^1(B, \mathbb{R}^3)$  with  $\text{Tr } X \in L^\infty(\partial B, \mathbb{R}^3)$ :

$$\begin{aligned} \|X\|_2^2 &\leq k_1(\|\nabla X\|_2^2 + \|X\|_{L^2(\partial B, \mathbb{R}^3)}^2) \\ &\leq k_2(D(X)) + \|X\|_{L^2(\partial B, \mathbb{R}^3)}^2 \leq kD(X) + k(\Gamma), \end{aligned}$$

with  $k_1, k_2, k$  and  $k(\Gamma)$  positive constants.

Then  $D_H$  is weakly lower semicontinuous and coercive in  $C^*(\Gamma)$ , and  $C^*(\Gamma)$  is a weakly closed subset of  $H^1(B, \mathbb{R}^3)$ , so there is a minimum  $\underline{X}$  of  $D_H$  in  $C^*(\Gamma)$ .

By conformal invariance of  $D_H$  ([5] and Lemma 1 below):

$$D_H(\underline{X}) = \inf_{C^*(\Gamma)} D_H(X) = \int_{C(\Gamma)} D_H(X).$$

But  $\underline{X} + \epsilon\varphi \in C(\Gamma)$  for  $\varphi \in C_0^1(B, \mathbb{R}^3)$ , then we have that  $dD_H(X)(\varphi) = 0$  and from Lemma 1 [4]:

$$\int_B \nabla \underline{X} \cdot \nabla \varphi + 2H(\underline{X})\underline{X}_u \wedge \underline{X}_v \cdot \varphi = 0 \text{ for } \varphi \in C_0^1(B, \mathbb{R}^3).$$

Finally, as in [5] for the case  $H = H_0 \in \mathbb{R}$ , from Lemma 1 we have that

$$\left. \frac{d}{d\epsilon} D_H(X \circ g_\epsilon^{-1}, B_\epsilon) \right|_{\epsilon=0} = \left. \frac{d}{d\epsilon} D(X \circ g_\epsilon^{-1}, B_\epsilon) \right|_{\epsilon=0} = 0$$

for any family of diffeomorphisms  $g_\epsilon : B \rightarrow B_\epsilon$ , with  $g_0 = \text{id}$  and  $\det (dg) = g_{\epsilon 1u}g_{\epsilon 2v} - g_{\epsilon 2u}g_{\epsilon 1v} > 0$ ; hence the coordinates  $(u, v)$  are isothermal.

Let us recall that a function  $g \in H^1(B, \mathbb{R}^3)$  is a solution to the classical Plateau problem for a curve  $\Gamma$  in  $\mathbb{R}^3$  if  $g$  is harmonic in  $B$  and satisfies (2) and (3) in (P).

**Theorem 2.** *Let  $\Gamma \subset \mathbb{R}^3$  be a rectifiable curve such that the solution to the classical Plateau problem is a function  $g \in W^{2,\infty}(B, \mathbb{R}^3)$  and suppose that  $H : \mathbb{R}^3 \rightarrow \mathbb{R}$  is a function satisfying the following properties:*

- i)  $H \in C^1(\mathbb{R}^3) \cap W^{1,\infty}(\mathbb{R}^3)$  and  $Q \in L^\infty(\mathbb{R}^3, \mathbb{R}^3)$
- ii)  $0 < \|H\|_\infty \|g\|_\infty < \frac{3}{2}$
- iii) *There exists a positive number  $c > \|\nabla g\|_\infty$  such that*

$$|H(\xi)| \leq \left(\frac{\lambda_1}{c}\right)^2 (|\xi| - \|g\|_\infty)_+ \text{ for } \xi \in \mathbb{R}^3,$$

where  $\lambda_1 > 0$  is the first eigenvalue of  $-\Delta$  in  $H_0^1(B)$ .

Then  $g$  is a weak solution of (P) and either  $g$  is a local minimum of  $D_H$  in

$$W^{2,\infty}(B, \mathbb{R}^3) \cap \{X \in H^2(B, \mathbb{R}^3); \operatorname{Tr} X = \operatorname{Tr} g,$$

$$\left. \operatorname{Tr} \frac{\partial X}{\partial r} = \operatorname{Tr} \frac{\partial g}{\partial r}, \operatorname{Tr} \frac{\partial X}{\partial \sigma} = \operatorname{Tr} \frac{\partial g}{\partial \sigma} \right\}.$$

or there exists a sequence  $X_n$  in  $W^{2,\infty}(B, \mathbb{R}^3)$  of distinct weak solutions of (P) with  $X_n \rightarrow g$  in  $W^{2,\infty}(B, \mathbb{R}^3)$ .

*Proof.* From iii),  $H(g) = 0$  on  $B$ , so (P) holds trivially. Now we choose a positive number  $\delta_1$  such that

$$\delta_1 < \min\{c - \|\nabla g\|_\infty, \frac{3}{2\|H\|_\infty} - \|g\|_\infty\}$$

and define

$$M_1 = \{g + \varphi; \varphi \in H^2(B, \mathbb{R}^3), \operatorname{Tr} \frac{\partial \varphi}{\partial r} = \operatorname{Tr} \frac{\partial \varphi}{\partial \sigma} = \operatorname{Tr} \varphi = 0, \|\varphi\|_{W^{2,\infty}} < \delta_1\}.$$

We have that  $M_1$  is a nonempty convex, closed and bounded subset of  $H^2(B, \mathbb{R}^3)$  and by Lemma 2 [4],  $D_H$  is weakly lower semicontinuous in  $M_1$ , because  $\|Q(X)\|_\infty \leq \|H\|_\infty \|X\|_\infty \leq \|H\|_\infty (\|X - g\|_\infty + \|g\|_\infty) < 3/2$  for  $X \in M_1$ . Hence there exists  $X_1 \in M_1$  such that

$$D_H(X_1) = \inf_{X \in M_1} D_H(X).$$

Suppose that  $g$  is not a local minimum of  $D_H$  in

$$W^{2,\infty}(B, \mathbb{R}^3) \cap \{X \in H^2(B, \mathbb{R}^3); \operatorname{Tr} X = \operatorname{Tr} g,$$

$$\left. \operatorname{Tr} \frac{\partial X}{\partial r} = \operatorname{Tr} \frac{\partial g}{\partial r}, \operatorname{Tr} \frac{\partial X}{\partial \sigma} = \operatorname{Tr} \frac{\partial g}{\partial \sigma} \right\}.$$

As in the proof of theorem 2 in [4], we have that  $dD_H(X_1)(\varphi) = 0$  for all  $\varphi \in C_0^1(B, \mathbb{R}^3)$ . From this and from  $X_1 \in H^2(B, \mathbb{R}^3)$ , it follows that (1) in (P) is fulfilled.  $g \in H^2(B, \mathbb{R}^3)$  is a solution to the Plateau problem, in particular

$$\left| \frac{\partial g}{\partial \sigma} \right| - \left| \frac{\partial g}{\partial \eta} \right| = \frac{\partial}{\partial \sigma} \cdot \frac{\partial g}{\partial \eta} = 0$$

on  $\bar{B}$ . From  $X_1 \in M_1$  we obtain that  $(\eta, \sigma)$  are isothermal on  $\partial B$  for  $X_1$ , so  $(u, v)$  are also isothermal on  $\partial B$  and in  $B$  (Lemma 2 below). Finally,  $\operatorname{Tr} g = \operatorname{Tr} X_1$  on  $\partial B$  with  $g \in C(\Gamma)$  gives (3) in (P). Now we choose

$$\delta_2 = \min\{\delta_1, \|X_1 - g\|_{W^{2,\infty}}\}$$

and define

$$M_2 = \{g + \varphi; \varphi \in W^{2,\infty}(B, \mathbb{R}^3), \text{Tr } \frac{\partial \varphi}{\partial r} = \text{Tr } \frac{\partial \varphi}{\partial \sigma} = \text{Tr } \varphi = 0 \|\varphi\|_{W^{2,\infty}} \leq \delta_2\}.$$

Then there exists  $X_2 \in M_2$  such that

$$d_H(X_2) = \inf_{X \in M_2} D_H(X).$$

$X_2$  is a weak solution of (P) and  $X_2 \neq g, X_1$ , because  $X_1 \notin M_2$ . Hence we can define a sequence  $(X_n) \subset W^{2,\infty}(B, \mathbb{R}^3)$  of weak solutions of (P) such that  $X_n \rightarrow g$  in  $W^{2,\infty}(B, \mathbb{R}^3)$ .

*Remark.* If  $\|Q\|_\infty < 3/2$ , the condition  $\|H\|_\infty \|g\|_\infty < 3/2$  is not necessary. In this case, we can define the sequence of convex subsets of  $W^{2,\infty}(B, \mathbb{R}^3)$  as follows:

$$M_1 = \{g + \varphi; \varphi \in W^{2,\infty}(B, \mathbb{R}^3), \text{Tr } \frac{\partial \varphi}{\partial r} = \text{Tr } \frac{\partial \varphi}{\partial \sigma} = \text{Tr } \varphi = 0 \text{ and}$$

$$\|\varphi\|_{W^{2,\infty}} \leq c - \|\nabla g\|_{W^{2,\infty}}\},$$

$$\delta_2 = \min\{c - \|\nabla g\|_\infty, \frac{1}{2}\|X_1 - g\|_{W^{2,\infty}}\}$$

and

$$M_2 = \{g + \varphi; \varphi \in W^{2,\infty}(B, \mathbb{R}^3), \text{Tr } \frac{\partial \varphi}{\partial r} = \text{Tr } \frac{\partial \varphi}{\partial \sigma} = \text{Tr } \varphi = 0 \|\varphi\|_{W^{2,\infty}} \leq \delta_2\}.$$

A class of functions  $H$  which are examples of our results is given by

$$H(\xi) = \begin{cases} H_0 & \xi_i \in (a_i, b_i) \\ 0 & \xi_i \notin (a_i - \epsilon, b_i + \epsilon) \end{cases}$$

with  $H_0, \epsilon, a_i, b_i, i = 1, 2, 3$  positive numbers such that  $0 < a_i - \epsilon, a_i < b_i$  and  $H_0(\sum_{i=1}^3 (b_i + \epsilon)^2)^{1/2} < 3/2$ . We suppose that  $H \in C^1(\mathbb{R}^3)$  and  $\|H\|_\infty = H_0$ .

As in [4],  $\|Q\|_\infty < \frac{3}{2}$  and  $\frac{\partial Q}{\partial \xi_i} \in L^\infty$  follow.

*Remark.* No assumptions are made on  $\Gamma$ .

### §3. TECHNICAL LEMMAS

We have as in the case  $H \equiv \text{cte}$ :

**Lemma 1.** *If the function  $Q$  associated to  $H$  satisfies  $Q \in L^\infty(\mathbb{R}^3, \mathbb{R}^3)$ , the Hildebrandt volume  $V(X) = \frac{1}{3} \int_B Q(X) \cdot X_u \wedge X_v$  is invariant under orientation preserving reparametrizations of  $X$ , i.e. if  $g \in C^1(\bar{B}, \mathbb{R}^2)$  is a diffeomorphism of  $B$  onto a domain  $\hat{B}$  with  $\det(dg) = g_{1u}g_{2v} - g_{2u}g_{1v} > 0$ , then  $V(X) = V(X \circ g^{-1})$ .*

**Lemma 2.** Let  $H : \mathbb{R}^3 \rightarrow \mathbb{R}$  continuous and bounded and  $X \in H^2(B, \mathbb{R}^3)$  such that  $\Delta X = 2H(X)X_u X_v$  in  $B$ . Then  $(\eta, \sigma)$  are isothermal on  $\partial B$  if and only if  $(u, v)$  are isothermal in  $B$ .

*Proof.* Suppose that  $|X_\eta|^2 - |X_\sigma|^2 = X_\eta \cdot X_\sigma = 0$  on  $\partial B$ , then  $|X_u|^2 - |X_v|^2 = X_u \cdot X_v = 0$  on  $\partial B$  by calculation. We extend  $X$  to  $\mathbb{R}^2$  by a reflection, setting

$$Y(u, v) = \begin{cases} X(u, v) & \text{in } \bar{B} \\ X\left(\frac{u}{r^2}, \frac{v}{r^2}\right) & \text{in } \mathbb{R}^2 - \bar{B} \text{ where } u^2 + v^2 = r^2. \end{cases}$$

A direct computation shows that

$$\begin{cases} \Delta Y = 2H(Y)Y_u \wedge Y_v & \text{in } B \\ \Delta Y = -2H(Y)Y_u \wedge Y_v & \text{in } \mathbb{R}^2 - \bar{B} \end{cases}$$

If we consider the conformal measure function

$$F(u, v) = |Y_u|^2 - |Y_v|^2 - 2iY_u \cdot Y_v,$$

we have that  $F$  is holomorphic in  $\mathbb{C} - \partial B$  and  $F \in C^0(\mathbb{C}, \mathbb{C})$ , because

$$\begin{aligned} \lim_{\substack{r \rightarrow 1 \\ r > 1}} (|Y_u|^2 - |Y_v|^2) &= [|X_u|^2(v^2 - u^2)^2 \\ &+ |X_v|^2 4u^2 v^2 + 2X_u \cdot X_v(v^2 - u^2)(-2uv)] \\ &[|X_u|^2(-2uv)^2 + |X_v|^2(u^2 - v^2)^2 + X_u \cdot X_v(u^2 - v^2)(-2uv)] \\ &= (|X_u|^2 - |X_v|^2)[(v^2 - u^2)^2 - 4u^2 v^2] + 2X_u \cdot X_v(u^2 - v^2)4uv \\ &= 0 = \lim_{\substack{r \rightarrow 1 \\ r < 1}} (|Y_u|^2 - |Y_v|^2) \end{aligned}$$

and

$$\begin{aligned} \lim_{\substack{r \rightarrow 1 \\ r > 1}} Y_u \cdot Y_v &= (|X_u|^2 - |X_v|^2)[(v^2 - u^2)(-2uv)] \\ &+ X_u \cdot X_v[-(u^2 - v^2)^2 + 4u^2 v^2] \\ &= 0 = \lim_{\substack{r \rightarrow 1 \\ r < 1}} Y_u \cdot Y_v. \end{aligned}$$

Then  $F$  is holomorphic in  $\mathbb{C}$ ; but from

$$\begin{aligned} \int_{\mathbb{R}^2} |F(u, v)| &\leq 2 \int_{\mathbb{R}^3} (|Y_u|^2 + |Y_v|^2) = 4 \int_B (|Y_u|^2 + |Y_v|^2) \\ &= 4 \int_B (|X_u|^2 + |X_v|^2) < +\infty \end{aligned}$$

we deduce that  $F \equiv 0$  and then we have  $|X_u|^2 - |X_v|^2 = X_u \cdot X_v = 0$  in  $B$ . Conversely, if  $(u, v)$  are isothermal in  $B$ , so are  $(r, \sigma)$ , because  $(u, v) \rightarrow (r, \sigma)$  is conformal; hence on  $\partial B$ ,  $(r, \sigma) \equiv (\eta, \sigma)$  are isothermal.

## §4. A NON EXISTENCE RESULT AND NECESSARY CONDITIONS

Taking into account the case  $H = H_0 \in \mathbb{R}$  and the Heinz' non existence result [5], [2], we have the following:

**Theorem 3.** Let  $\Gamma \subset \mathbb{R}^3$  be a rectifiable Jordan curve of length  $L(\Gamma)$ ,  $H \in C(\mathbb{R}^3)$ , and suppose that there exists a positive number  $\delta$  having the properties

- i)  $L(\Gamma) < \delta$ .
- ii) For any  $X \in C(\Gamma)$  there exists a unit vector  $\eta_X \in \mathbb{R}^3$  such that

$$\eta_X \cdot \int_B 2H(X)X_u \wedge X_v \geq \delta.$$

Then there is no solution to (P) in  $C^1(\bar{B}, \mathbb{R}^3) \cap C^2(B, \mathbb{R}^3)$ .

*Proof.* Suppose that  $X \in C^1(\bar{B}, \mathbb{R}^3) \cap C^2(B, \mathbb{R}^3)$  is a solution of (P). Then

$$\begin{aligned} \eta_X \cdot \int_B 2H(X)X_u \cdot X_v &= \eta_X \cdot \int_B \Delta X = \eta_X \cdot \int_{\partial B} \frac{\partial X}{\partial \eta} d\sigma \\ &\leq \int_{\partial B} \left| \frac{\partial X}{\partial \eta} \right| d\sigma = \int_{\partial B} \left| \frac{\partial X}{\partial \sigma} \right| d\sigma = L(\Gamma) < \delta. \end{aligned}$$

A contradiction.

**Theorem 4.** Let  $\Gamma \subset \mathbb{R}^3$  be a rectifiable Jordan curve of length  $L(\Gamma)$ ,  $H : \mathbb{R}^3 \rightarrow \mathbb{R}$  continuous and bounded, and suppose that  $X \in C^1(\bar{B}, \mathbb{R}^3) \cap C^2(B, \mathbb{R}^3)$  is a solution of (P) verifying  $\|H(X)X\|_\infty < 1$ . Then

$$D(X) \leq \frac{L(\Gamma)\|X\|_\infty}{2(1 - \|H(X)X\|_\infty)}.$$

*Proof.* We have that  $\Delta X = 2H(X)X_u \wedge X_v$  in  $B$ . Thus

$$\begin{aligned} 0 &= \int_B [-\Delta X + 2H(X)X_u \wedge X_v] \cdot X \\ &= \int_B [|\nabla X|^2 + 2H(X)X_u \wedge X_v \cdot X] - \int_{\partial B} \frac{\partial X}{\partial \eta} \cdot X d\sigma \\ &\geq 2D(X) - 2\|H(X)X\|_\infty \int_B |X_u \wedge X_v| - \|X\|_\infty \int_{\partial B} \left| \frac{\partial X}{\partial \eta} \right| d\sigma \\ &\geq 2D(X)(1 - \|H(X)X\|_\infty) - \|X\|_\infty \int_{\partial B} \left| \frac{\partial X}{\partial \sigma} \right| d\sigma \\ &= 2D(X)(1 - \|H(X)X\|_\infty) - \|X\|_\infty L(\Gamma). \end{aligned}$$

It follows now that

$$D(X) \leq \frac{L(\Gamma)\|X\|_\infty}{2(1 - \|H(X)X\|_\infty)}.$$



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