

# More on $\lambda$ -closed sets in topological spaces

Más sobre conjuntos  $\lambda$ -cerrados en espacios topológicos

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**ABSTRACT.** In this paper, we introduce and study topological properties of  $\lambda$ -derived,  $\lambda$ -border,  $\lambda$ -frontier and  $\lambda$ -exterior of a set using the concept of  $\lambda$ -open sets. We also present and study new separation axioms by using the notions of  $\lambda$ -open and  $\lambda$ -closure operator.

*Key words and phrases.* Topological spaces,  $\Lambda$ -sets,  $\lambda$ -open sets,  $\lambda$ -closed sets,  $\lambda$ - $R_0$  spaces,  $\lambda$ - $R_1$  spaces.

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**RESUMEN.** En este artículo introducimos y estudiamos propiedades topológicas de  $\lambda$ -derivada,  $\lambda$ -borde,  $\lambda$ -frontera y  $\lambda$ -exterior de un conjunto usando el concepto de  $\lambda$ -conjunto abierto. Presentamos un nuevo estudio de axiomas de separación usando las nociones de operador  $\lambda$ -abierto y  $\lambda$ -clausura.

*Palabras y frases clave.* Espacios topológicos,  $\Lambda$ -conjuntos, conjuntos  $\lambda$ -abiertos, conjuntos  $\lambda$ -cerrados, espacios  $\lambda$ - $R_0$ , espacios  $\lambda$ - $R_1$ .

## 1. Introduction

Maki [12] introduced the notion of  $\Lambda$ -sets in topological spaces. A  $\Lambda$ -set is a set  $A$  which is equal to its kernel(= saturated set), i.e. to the intersection of all open supersets of  $A$ . Arenas et al. [1] introduced and investigated the notion of  $\lambda$ -closed sets and  $\lambda$ -open sets by involving  $\Lambda$ -sets and closed sets. This enabled them to obtain some nice results. In this paper, for these sets, we introduce the notions of  $\lambda$ -derived,  $\lambda$ -border,  $\lambda$ -frontier and  $\lambda$ -exterior of a set and show that some of their properties are analogous to those for open

sets. Also, we give some additional properties of  $\lambda$ -closure. Moreover, we offer and study new separation axioms by utilizing the notions of  $\lambda$ -open sets and  $\lambda$ -closure operator.

Throughout this paper we adopt the notations and terminology of [12] and [1] and the following conventions:  $(X, \tau)$ ,  $(Y, \sigma)$  and  $(Z, \nu)$  (or simply  $X$ ,  $Y$  and  $Z$ ) will always denote spaces on which no separation axioms are assumed unless explicitly stated.

**Definition 1.** Let  $B$  be a subset of a space  $(X, \tau)$ .  $B$  is a  $\Lambda$ -set (resp.  $V$ -set) [12] if  $B = B^\Lambda$  (resp.  $B = B^V$ ), where:

$$B^\Lambda = \bigcap \{U \mid U \supset B, U \in \tau\} \quad \text{and} \quad B^V = \bigcup \{F \mid B \supset F, F^c \in \tau\}.$$

**Theorem 1.1** ([12]). Let  $A$ ,  $B$  and  $\{B_i \mid i \in I\}$  be subsets of a space  $(X, \tau)$ . Then the following properties are valid:

- a)  $B \subset B^\Lambda$ .
- b) If  $A \subset B$  then  $A^\Lambda \subset B^\Lambda$ .
- c)  $B^{\Lambda\Lambda} = B^\Lambda$ .
- d)  $\left(\bigcup_{i \in I} B_i\right)^\Lambda = \bigcup_{i \in I} B_i^\Lambda$ .
- e) If  $B \in \tau$ , then  $B = B^\Lambda$  (i.e.  $B$  is a  $\Lambda$ -set).
- f)  $(B^c)^\Lambda = (B^V)^c$ .
- g)  $B^V \subset B$ .
- h) If  $B^c \in \tau$ , then  $B = B^V$  (i.e.  $B$  is a  $V$ -set).
- i)  $\left(\bigcap_{i \in I} B_i\right)^\Lambda \subset \bigcap_{i \in I} B_i^\Lambda$ .
- j)  $\left(\bigcup_{i \in I} B_i\right)^V \supset \bigcup_{i \in I} B_i^V$ .
- k) If  $B_i$  is a  $\Lambda$ -set ( $i \in I$ ), then  $\bigcup_{i \in I} B_i$  is a  $\Lambda$ -set.
- l) If  $B_i$  is a  $\Lambda$ -set ( $i \in I$ ), then  $\bigcap_{i \in I} B_i$  is a  $\Lambda$ -set.
- m)  $B$  is a  $\Lambda$ -set if and only if  $B^c$  is a  $V$ -set.
- n) The subsets  $\emptyset$  and  $X$  are  $\Lambda$ -sets.

## 2. Applications of $\lambda$ -closed sets and $\lambda$ -open sets

**Definition 2.** A subset  $A$  of a space  $(X, \tau)$  is called  $\lambda$ -closed [1] if  $A = B \cap C$ , where  $B$  is a  $\Lambda$ -set and  $C$  is a closed set.

**Lemma 2.1.** For a subset  $A$  of a space  $(X, \tau)$ , the following statements are equivalent [1]:

- (a)  $A$  is  $\lambda$ -closed.
- (b)  $A = L \cap Cl(A)$ , where  $L$  is a  $\Lambda$ -set.
- (c)  $A = A^\Lambda \cap Cl(A)$ .

**Lemma 2.2.** *Every  $\Lambda$ -set is a  $\lambda$ -closed set.*

*Proof.* Take  $A \cap X$ , where  $A$  is a  $\Lambda$ -set and  $X$  is closed. □

**Remark 2.3.** [1]. *Since locally closed sets and  $\lambda$ -sets are concepts independent of each other, then a  $\lambda$ -closed set need not be locally closed or be a  $\Lambda$ -set. Moreover, in each  $T_0$  non- $T_1$  space there are singletons which are  $\lambda$ -closed but not a  $\Lambda$ -set.*

**Definition 3.** *A subset  $A$  of a space  $(X, \tau)$  is called  $\lambda$ -open if  $A^c = X \setminus A$  is  $\lambda$ -closed.*

We denote the collection of all  $\lambda$ -open (resp.  $\lambda$ -closed) subsets of  $X$  by  $\lambda O(X)$  or  $\lambda O(X, \tau)$  (resp.  $\lambda C(X)$  or  $\lambda C(X, \tau)$ ). We set  $\lambda O(X, x) = \{V \in \lambda O(X) \mid x \in V\}$  for  $x \in X$ . We define similarly  $\lambda C(X, x)$ .

**Theorem 2.4.** *The following statements are equivalent for a subset  $A$  of a topological space  $X$ :*

- (a)  $A$  is  $\lambda$ -open.
- (b)  $A = T \cup C$ , where  $T$  is a  $V$ -set and  $C$  is an open set.

**Lemma 2.5.** *Every  $V$ -set is  $\lambda$ -open.*

*Proof.* Take  $A = A \cup \emptyset$ , where  $A$  is  $V$ -set,  $X$  is  $\Lambda$ -set and  $\emptyset = X \setminus X$ . □

**Definition 4.** *Let  $(X, \tau)$  be a space and  $A \subset X$ . A point  $x \in X$  is called  $\lambda$ -cluster point of  $A$  if for every  $\lambda$ -open set  $U$  of  $X$  containing  $x$ ,  $A \cap U \neq \emptyset$ . The set of all  $\lambda$ -cluster points is called the  $\lambda$ -closure of  $A$  and is denoted by  $Cl_\lambda(A)$ .*

**Lemma 2.6.** *Let  $A, B$  and  $A_i$  ( $i \in I$ ) be subsets of a topological space  $(X, \tau)$ . The following properties hold:*

- (1) *If  $A_i$  is  $\lambda$ -closed for each  $i \in I$ , then  $\cap_{i \in I} A_i$  is  $\lambda$ -closed.*
- (2) *If  $A_i$  is  $\lambda$ -open for each  $i \in I$ , then  $\cup_{i \in I} A_i$  is  $\lambda$ -open.*
- (3)  *$A$  is  $\lambda$ -closed if and only if  $A = Cl_\lambda(A)$ .*
- (4)  *$Cl_\lambda(A) = \cap \{F \in \lambda C(X, \tau) \mid A \subset F\}$ .*
- (5)  *$A \subset Cl_\lambda(A) \subset Cl(A)$ .*
- (6) *If  $A \subset B$ , then  $Cl_\lambda(A) \subset Cl_\lambda(B)$ .*
- (7)  *$Cl_\lambda(A)$  is  $\lambda$ -closed.*

*Proof.* (1) It is shown in [1], 3.3

(2) It is an immediate consequence of (1).

(3) Straightforward.

(4) Let  $H = \cap \{F \mid A \subset F, F \text{ is } \lambda\text{-closed}\}$ . Suppose that  $x \in H$ . Let  $U$  be a  $\lambda$ -open set containing  $x$  such that  $A \cap U = \emptyset$ . And so,  $A \subset X \setminus U$ . But  $X \setminus U$  is  $\lambda$ -closed and hence  $Cl_\lambda(A) \subset X \setminus U$ . Since  $x \notin X \setminus U$ , we obtain  $x \notin Cl_\lambda(A)$  which is contrary to the hypothesis.

On the other hand, suppose that  $x \in Cl_\lambda(A)$ , i.e., that every  $\lambda$ -open set of  $X$  containing  $x$  meets  $A$ . If  $x \notin H$ , then there exists a  $\lambda$ -closed set  $F$  of  $X$

such that  $A \subset F$  and  $x \notin F$ . Therefore  $x \in X \setminus F \in \lambda O(X)$ . Hence  $X \setminus F$  is a  $\lambda$ -open set of  $X$  containing  $x$ , but  $(X \setminus F) \cap A = \emptyset$ . But this is a contradiction and thus the claim.

(5) It follows from the fact that every closed set is  $\lambda$ -closed. ☑

In general the converse of 2.6(5) may not be true.

**Example 2.7.** Let  $X = \{a, b, c\}$ ,  $\tau = \{\emptyset, \{a\}, \{b\}, \{a, b\}, X\}$ . Then  $Cl(\{a\}) = \{a, c\} \not\subset Cl_\lambda(\{a\}) = \{a\}$ .

**Definition 5.** Let  $A$  be a subset of a space  $X$ . A point  $x \in X$  is said to be  $\lambda$ -limit point of  $A$  if for each  $\lambda$ -open set  $U$  containing  $x$ ,  $U \cap (A \setminus \{x\}) \neq \emptyset$ . The set of all  $\lambda$ -limit points of  $A$  is called a  $\lambda$ -derived set of  $A$  and is denoted by  $D_\lambda(A)$ .

**Theorem 2.8.** For subsets  $A, B$  of a space  $X$ , the following statements hold:

- (1)  $D_\lambda(A) \subset D(A)$  where  $D(A)$  is the derived set of  $A$ .
- (2) If  $A \subset B$ , then  $D_\lambda(A) \subset D_\lambda(B)$ .
- (3)  $D_\lambda(A) \cup D_\lambda(B) \subset D_\lambda(A \cup B)$  and  $D_\lambda(A \cap B) \subset D_\lambda(A) \cap D_\lambda(B)$ .
- (4)  $D_\lambda(D_\lambda(A)) \setminus A \subset D_\lambda(A)$ .
- (5)  $D_\lambda(A \cup D_\lambda(A)) \subset A \cup D_\lambda(A)$ .

*Proof.* (1) It suffices to observe that every open set is  $\lambda$ -open.

(3) it is an immediate consequence of (2).

(4) If  $x \in D_\lambda(D_\lambda(A)) \setminus A$  and  $U$  is a  $\lambda$ -open set containing  $x$ , then  $U \cap (D_\lambda(A) \setminus \{x\}) \neq \emptyset$ . Let  $y \in U \cap (D_\lambda(A) \setminus \{x\})$ . Then since  $y \in D_\lambda(A)$  and  $y \in U$ ,  $U \cap (A \setminus \{y\}) \neq \emptyset$ . Let  $z \in U \cap (A \setminus \{y\})$ . Then  $z \neq x$  for  $z \in A$  and  $x \notin A$ . Hence  $U \cap (A \setminus \{x\}) \neq \emptyset$ . Therefore  $x \in D_\lambda(A)$ .

(5) Let  $x \in D_\lambda(A \cup D_\lambda(A))$ . If  $x \in A$ , the result is obvious. So let  $x \in D_\lambda(A \cup D_\lambda(A)) \setminus A$ , then for  $\lambda$ -open set  $U$  containing  $x$ ,  $U \cap (A \cup D_\lambda(A) \setminus \{x\}) \neq \emptyset$ . Thus  $U \cap (A \setminus \{x\}) \neq \emptyset$  or  $U \cap (D_\lambda(A) \setminus \{x\}) \neq \emptyset$ . Now it follows from (4) that  $U \cap (A \setminus \{x\}) \neq \emptyset$ . Hence  $x \in D_\lambda(A)$ . Therefore, in any case  $D_\lambda(A \cup D_\lambda(A)) \subset A \cup D_\lambda(A)$ . ☑

In general the converse of (1) may not be true and the equality does not hold in (3) of Theorem 2.8.

**Example 2.9.** Let  $X = \{a, b, c\}$  with topology  $\tau = \{\emptyset, \{a\}, \{a, c\}, X\}$ . Thus  $\lambda O(X, \tau) = \{\emptyset, \{a\}, \{c\}, \{a, b\}, \{a, c\}, \{b, c\}, X\}$ . Take:

- (i)  $A = \{a\}$ . We obtain  $D(A) \not\subset D_\lambda(A)$ .
- (ii)  $C = \{a\}$  and  $E = \{b, c\}$ . Then  $D_\alpha(C \cup E) \neq D_\alpha(C) \cup D_\alpha(E)$ .

**Theorem 2.10.** For any subset  $A$  of a space  $X$ ,  $Cl_\lambda(A) = A \cup D_\lambda(A)$ .

*Proof.* Since  $D_\lambda(A) \subset Cl_\lambda(A)$ ,  $A \cup D_\lambda(A) \subset Cl_\lambda(A)$ . On the other hand, let  $x \in Cl_\lambda(A)$ . If  $x \in A$ , then the proof is complete. If  $x \notin A$ , then each  $\lambda$ -open set  $U$  containing  $x$  intersects  $A$  at a point distinct from  $x$ . Therefore  $x \in D_\lambda(A)$ . Thus  $Cl_\lambda(A) \subset A \cup D_\lambda(A)$  which completes the proof. ☑

**Definition 6.** A point  $x \in X$  is said to be a  $\lambda$ -interior point of  $A$  if there exists a  $\lambda$ -open set  $U$  containing  $x$  such that  $U \subset A$ . The set of all  $\lambda$ -interior points of  $A$  is said to be  $\lambda$ -interior of  $A$  and is denoted by  $Int_\lambda(A)$ .

**Theorem 2.11.** For subsets  $A, B$  of a space  $X$ , the following statements are true:

- (1)  $Int_\lambda(A)$  is the largest  $\lambda$ -open set contained in  $A$ .
- (2)  $A$  is  $\lambda$ -open if and only if  $A = Int_\lambda(A)$ .
- (3)  $Int_\lambda(Int_\lambda(A)) = Int_\lambda(A)$ .
- (4)  $Int_\lambda(A) = A \setminus D_\lambda(X \setminus A)$ .
- (5)  $X \setminus Int_\lambda(A) = Cl_\lambda(X \setminus A)$ .
- (6)  $X \setminus Cl_\lambda(A) = Int_\lambda(X \setminus A)$ .
- (7)  $A \subset B$ , then  $Int_\lambda(A) \subset Int_\lambda(B)$ .
- (8)  $Int_\lambda(A) \cup Int_\lambda(B) \subset Int_\lambda(A \cup B)$ .
- (9)  $Int_\lambda(A) \cap Int_\lambda(B) \supset Int_\lambda(A \cap B)$ .

*Proof.* (4) If  $x \in A \setminus D_\lambda(X \setminus A)$ , then  $x \notin D_\lambda(X \setminus A)$  and so there exists a  $\lambda$ -open set  $U$  containing  $x$  such that  $U \cap (X \setminus A) = \emptyset$ . Then  $x \in U \subset A$  and hence  $x \in Int_\lambda(A)$ , i.e.,  $A \setminus D_\lambda(X \setminus A) \subset Int_\lambda(A)$ . On the other hand, if  $x \in Int_\lambda(A)$ , then  $x \notin D_\lambda(X \setminus A)$  since  $Int_\lambda(A)$  is  $\lambda$ -open and  $Int_\lambda(A) \cap (X \setminus A) = \emptyset$ . Hence  $Int_\lambda(A) = A \setminus D_\lambda(X \setminus A)$ .

(5)  $X \setminus Int_\lambda(A) = X \setminus (A \setminus D_\lambda(X \setminus A)) = (X \setminus A) \cup D_\lambda(X \setminus A) = Cl_\lambda(X \setminus A)$ . □

**Definition 7.**  $b_\lambda(A) = A \setminus Int_\lambda(A)$  is said to be the  $\lambda$ -border of  $A$ .

**Theorem 2.12.** For a subset  $A$  of a space  $X$ , the following statements hold:

- (1)  $b_\lambda(A) \subset b(A)$  where  $b(A)$  denotes the border of  $A$ .
- (2)  $A = Int_\lambda(A) \cup b_\lambda(A)$ .
- (3)  $Int_\lambda(A) \cap b_\lambda(A) = \emptyset$ .
- (4)  $A$  is a  $\lambda$ -open set if and only if  $b_\lambda(A) = \emptyset$ .
- (5)  $b_\lambda(Int_\lambda(A)) = \emptyset$ .
- (6)  $Int_\lambda(b_\lambda(A)) = \emptyset$ .
- (7)  $b_\lambda(b_\lambda(A)) = b_\lambda(A)$ .
- (8)  $b_\lambda(A) = A \cap Cl_\lambda(X \setminus A)$ .
- (9)  $b_\lambda(A) = D_\lambda(X \setminus A)$ .

*Proof.* (6) If  $x \in Int_\lambda(b_\lambda(A))$ , then  $x \in b_\lambda(A)$ . On the other hand, since  $b_\lambda(A) \subset A$ ,  $x \in Int_\lambda(b_\lambda(A)) \subset Int_\lambda(A)$ . Hence  $x \in Int_\lambda(A) \cap b_\lambda(A)$  which contradicts (3). Thus  $Int_\lambda(b_\lambda(A)) = \emptyset$ .

(8)  $b_\lambda(A) = A \setminus Int_\lambda(A) = A \setminus (X \setminus Cl_\lambda(X \setminus A)) = A \cap Cl_\lambda(X \setminus A)$ .

(9)  $b_\lambda(A) = A \setminus Int_\lambda(A) = A \setminus (A \setminus D_\lambda(X \setminus A)) = D_\lambda(X \setminus A)$ . □

**Definition 8.**  $Fr_\lambda(A) = Cl_\lambda(A) \setminus Int_\lambda(A)$  is said to be the  $\lambda$ -frontier of  $A$ .

**Theorem 2.13.** For a subset  $A$  of a space  $X$ , the following statements are hold:

- (1)  $Fr_\lambda(A) \subset Fr(A)$  where  $Fr(A)$  denotes the frontier of  $A$ .

- (2)  $Cl_\lambda(A) = Int_\lambda(A) \cup Fr_\lambda(A)$ .
- (3)  $Int_\lambda(A) \cap Fr_\lambda(A) = \emptyset$ .
- (4)  $b_\lambda(A) \subset Fr_\lambda(A)$ .
- (5)  $Fr_\lambda(A) = b_\lambda(A) \cup D_\lambda(A)$ .
- (6)  $A$  is a  $\lambda$ -open set if and only if  $Fr_\lambda(A) = D_\lambda(A)$ .
- (7)  $Fr_\lambda(A) = Cl_\lambda(A) \cap Cl_\lambda(X \setminus A)$ .
- (8)  $Fr_\lambda(A) = Fr_\lambda(X \setminus A)$ .
- (9)  $Fr_\lambda(A)$  is  $\lambda$ -closed.
- (10)  $Fr_\lambda(Fr_\lambda(A)) \subset Fr_\lambda(A)$ .
- (11)  $Fr_\lambda(Int_\lambda(A)) \subset Fr_\lambda(A)$ .
- (12)  $Fr_\lambda(Cl_\lambda(A)) \subset Fr_\lambda(A)$ .
- (13)  $Int_\lambda(A) = A \setminus Fr_\lambda(A)$ .

*Proof.* (2)  $Int_\lambda(A) \cup Fr_\lambda(A) = Int_\lambda(A) \cup (Cl_\lambda(A) \setminus Int_\lambda(A)) = Cl_\lambda(A)$ .  
 (3)  $Int_\lambda(A) \cap Fr_\lambda(A) = Int_\lambda(A) \cap (Cl_\lambda(A) \setminus Int_\lambda(A)) = \emptyset$ .  
 (5) Since  $Int_\lambda(A) \cup Fr_\lambda(A) = Int_\lambda(A) \cup b_\lambda(A) \cup D_\lambda(A)$ ;  $Fr_\lambda(A) = b_\lambda(A) \cup D_\lambda(A)$ .  
 (7)  $Fr_\lambda(A) = Cl_\lambda(A) \setminus Int_\lambda(A) = Cl_\lambda(A) \cap Cl_\lambda(X \setminus A)$ .  
 (9)  $Cl_\lambda(Fr_\lambda(A)) = Cl_\lambda(Cl_\lambda(A) \cap Cl_\lambda(X \setminus A)) \subset Cl_\lambda(Cl_\lambda(A)) \cap Cl_\lambda(Cl_\lambda(X \setminus A)) = Fr_\lambda(A)$ . Hence  $Fr_\lambda(A)$  is  $\lambda$ -closed.  
 (10)  $Fr_\lambda(Fr_\lambda(A)) = Cl_\lambda(Fr_\lambda(A)) \cap Cl_\lambda(X \setminus Fr_\lambda(A)) \subset Cl_\lambda(Fr_\lambda(A)) = Fr_\lambda(A)$ .  
 (12)  $Fr_\lambda(Cl_\lambda(A)) = Cl_\lambda(Cl_\lambda(A)) \setminus Int_\lambda(Cl_\lambda(A)) = Cl_\lambda(A) \setminus Int_\lambda(Cl_\lambda(A)) = Cl_\lambda(A) \setminus Int_\lambda(A) = Fr_\lambda(A)$ .  
 (13)  $A \setminus Fr_\lambda(A) = A \setminus (Cl_\lambda(A) \setminus Int_\lambda(A)) = Int_\lambda(A)$ . ✓

The converses of (1) and (4) of the Theorem 2.13 are not true in general as are shown by Example 2.14.

**Example 2.14.** Consider the topological space  $(X, \tau)$  given in Example 2.7. If  $A = \{a\}$ . Then  $Fr(A) \not\subseteq Fr_\lambda(A)$  and if  $B = \{a, c\}$ , then  $Fr_\lambda(B) \not\subseteq b_\lambda(B)$ .

Recall that a function  $f : (X, \tau) \rightarrow (Y, \sigma)$  is said to be  $\lambda$ -continuous [1] if  $f^{-1}(V) \in \lambda C(X)$  for every closed subset  $V$  of  $Y$ .

**Theorem 2.15.** For a function  $f : X \rightarrow Y$ , the following are equivalent:

- (1)  $f$  is  $\lambda$ -continuous;
- (2) for every open subset  $V$  of  $Y$ ,  $f^{-1}(V) \in \lambda O(X)$ ;
- (3) for each  $x \in X$  and each  $V \in O(Y, f(x))$ , there exists  $U \in \lambda O(X, x)$  such that  $f(U) \subset V$ .

*Proof.* (1)  $\rightarrow$  (2) : This follows from  $f^{-1}(Y \setminus V) = X \setminus f^{-1}(V)$ .  
 (1)  $\rightarrow$  (3) : Let  $V \in O(Y)$  and  $f(x) \in V$ . Since  $f$  is  $\lambda$ -continuous  $f^{-1}(V) \in \lambda O(X)$  and  $x \in f^{-1}(V)$ . Put  $U = f^{-1}(V)$ . Then  $x \in U$  and  $f(U) \subset V$ .  
 (3)  $\rightarrow$  (1) : Let  $V$  be an open set of  $Y$  and  $x \in f^{-1}(V)$ . Then  $f(x) \in V$ . Therefore by (3) there exists a  $U_x \in \lambda O(X)$  such that  $x \in U_x$  and  $f(U_x) \subset V$ . Therefore  $x \in U_x \subset f^{-1}(V)$ . This implies that  $f^{-1}(V)$  is a union of  $\lambda$ -open sets of  $X$ . Consequently  $f^{-1}(V) \in \lambda O(X)$ . Hence  $f$  is  $\lambda$ -continuous. ✓

In the following theorem  $\#\Lambda.c.$  denotes the set of points  $x$  of  $X$  for which a function  $f : (X, \tau) \rightarrow (Y, \sigma)$  is not  $\lambda$ -continuous.

**Theorem 2.16.**  $\#\Lambda.c.$  is identical with the union of the  $\lambda$ -frontiers of the inverse images of  $\lambda$ -open sets containing  $f(x)$ .

*Proof.* Suppose that  $f$  is not  $\lambda$ -continuous at a point  $x$  of  $X$ . Then there exists an open set  $V \subset Y$  containing  $f(x)$  such that  $f(U)$  is not a subset of  $V$  for every  $U \in \lambda O(X)$  containing  $x$ . Hence we have  $U \cap (X \setminus f^{-1}(V)) \neq \emptyset$  for every  $U \in \lambda O(X)$  containing  $x$ . It follows that  $x \in Cl_\lambda(X \setminus f^{-1}(V))$ . We also have  $x \in f^{-1}(V) \subset Cl_\lambda(f^{-1}(V))$ . This means that  $x \in Fr_\lambda(f^{-1}(V))$ .

Now, let  $f$  be  $\lambda$ -continuous at  $x \in X$  and  $V \subset Y$  be any open set containing  $f(x)$ . Then  $x \in f^{-1}(V)$  is a  $\lambda$ -open set of  $X$ . Thus  $x \in Int_\lambda(f^{-1}(V))$  and therefore  $x \notin Fr_\lambda(f^{-1}(V))$  for every open set  $V$  containing  $f(x)$ . □

**Definition 9.**  $Ext_\lambda(A) = Int_\lambda(X \setminus A)$  is said to be a  $\lambda$ -exterior of  $A$ .

**Theorem 2.17.** For a subset  $A$  of a space  $X$ , the following statements are hold:

- (1)  $Ext(A) \subset Ext_\lambda(A)$  where  $Ext(A)$  denotes the exterior of  $A$ .
- (2)  $Ext_\lambda(A)$  is  $\lambda$ -open.
- (3)  $Ext_\lambda(A) = Int_\lambda(X \setminus A) = X \setminus Cl_\lambda(A)$ .
- (4)  $Ext_\lambda(Ext_\lambda(A)) = Int_\lambda(Cl_\lambda(A))$ .
- (5) If  $A \subset B$ , then  $Ext_\lambda(A) \supset Ext_\lambda(B)$ .
- (6)  $Ext_\lambda(A \cup B) \subset Ext_\lambda(A) \cup Ext_\lambda(B)$ .
- (7)  $Ext_\lambda(A \cap B) \supset Ext_\lambda(A) \cap Ext_\lambda(B)$ .
- (8)  $Ext_\lambda(X) = \emptyset$ .
- (9)  $Ext_\lambda(\emptyset) = X$ .
- (10)  $Ext_\lambda(A) = Ext_\lambda(X \setminus Ext_\lambda(A))$ .
- (11)  $Int_\lambda(A) \subset Ext_\lambda(Ext_\lambda(A))$ .
- (12)  $X = Int_\lambda(A) \cup Ext_\lambda(A) \cup Fr_\lambda(A)$ .

*Proof.* (4)  $Ext_\lambda(Ext_\lambda(A)) = Ext_\lambda(X \setminus Cl_\lambda(A)) = Int_\lambda(X \setminus (X \setminus Cl_\lambda(A))) = Int_\lambda(Cl_\lambda(A))$ .

(10)  $Ext_\lambda(X \setminus Ext_\lambda(A)) = Ext_\lambda(X \setminus Int_\lambda(X \setminus A)) = Int_\lambda(X \setminus (X \setminus Int_\lambda(X \setminus A))) = Int_\lambda(Int_\lambda(X \setminus A)) = Int_\lambda(X \setminus A) = Ext_\lambda(A)$ .

(11)  $Int_\lambda(A) \subset Int_\lambda(Cl_\lambda(A)) = Int_\lambda(X \setminus Int_\lambda(X \setminus A)) = Int_\lambda(X \setminus Ext_\lambda(A)) = Ext_\lambda(Ext_\lambda(A))$ . □

**Example 2.18.** Consider the topological space  $(X, \tau)$  given in Example 2.7. Hence, if  $A = \{a\}$  and  $B = \{b\}$ , Then  $Ext_\lambda(A) \not\subset Ext(A)$ ,  $Ext_\lambda(A \cap B) \neq Ext_\lambda(A) \cap Ext_\lambda(B)$  and  $Ext_\lambda(A \cup B) \neq Ext_\lambda(A) \cup Ext_\lambda(B)$ .

### 3. Some new separation axioms

We recall with the following notions which will be used in the sequel:

A space  $(X, \tau)$  is said to be  $R_0$  [3] (resp.  $\lambda$ - $R_0$  [2]) if every open set contains the closure of each of its singletons. A space  $(X, \tau)$  is said to be  $R_1$  [3] (resp.  $\lambda$ - $R_1$  [2]) if for  $x, y$  in  $X$  with  $Cl(\{x\}) \neq Cl(\{y\})$ , there exist disjoint open sets  $U$  and  $V$  such that  $Cl(\{x\})$  is a subset of  $U$  and  $Cl(\{y\})$  is a subset of  $V$ . A space is  $T_0$  if for  $x, y \in X$  such that  $x \neq y$  there exists a open set  $U$  of  $X$  containing  $x$  but not  $y$  or an open set  $V$  of  $X$  containing  $y$  but not  $x$ . A space  $(X, \tau)$  is  $T_1$  if to each pair of distinct points  $x$  and  $y$  of  $X$ , there exists a pair of open sets one containing  $x$  but not  $y$  and the other containing  $y$  but not  $x$ . A space  $(X, \tau)$  is  $T_2$  if to each pair of distinct points  $x$  and  $y$  of  $X$ , there exists a pair of disjoint open sets, one containing  $x$  and the other containing  $y$ . Recall that a space  $(X, \tau)$  is called a  $T_{\frac{1}{2}}$ -space [11] if every generalized closed subset of  $X$  is closed or equivalently if every singleton is open or closed [6]. In [1], Arenas et al. have shown that a space  $(X, \tau)$  is called a  $T_{\frac{1}{2}}$ -space if and only if every subset of  $X$  is  $\lambda$ -closed.

**Definition 10.** Let  $X$  be a space. A subset  $A \subset X$  is called a  $\lambda$ -Difference set (in short  $\lambda$ -D-set) if there are two  $\lambda$ -open sets  $U, V$  in  $X$  such that  $U \neq X$  and  $A = U \setminus V$ .

It is true that every  $\lambda$ -open set  $U \neq X$  is a  $\lambda$ -D-set since  $U = U \setminus \emptyset$ .

**Definition 11.** A space  $(X, \tau)$  is said to be:

- (i)  $\lambda$ - $D_0$  (resp.  $\lambda$ - $D_1$ ) if for  $x, y \in X$  such that  $x \neq y$  there exists a  $\lambda$ -D-set of  $X$  containing  $x$  but not  $y$  or (resp. and) a  $\lambda$ -D-set containing  $y$  but not  $x$ .
- (ii) A topological space  $(X, \tau)$  is  $\lambda$ - $D_2$  if for  $x, y \in X$  such that  $x \neq y$  there exist disjoint  $\lambda$ -D-sets  $G$  and  $E$  such that  $x \in G$  and  $y \in E$ .
- (iii)  $\lambda$ - $T_0$  (resp.  $\lambda$ - $T_1$ ) if for  $x, y \in X$  such that  $x \neq y$  there exists a  $\lambda$ -open set  $U$  of  $X$  containing  $x$  but not  $y$  or (resp. and) a  $\lambda$ -open set  $V$  of  $X$  containing  $y$  but not  $x$ .
- (iv)  $\lambda$ - $T_2$  if for  $x, y \in X$  such that  $x \neq y$  there exist disjoint  $\lambda$ -open sets  $U$  and  $V$  such that  $x \in U$  and  $y \in V$ .

**Remark 3.1.**

- (i) If  $(X, \tau)$  is  $\lambda$ - $T_i$ , then it is  $\lambda$ - $T_{i-1}$ ,  $i = 1, 2$ .
- (ii) Obviously, if  $(X, \tau)$  is  $\lambda$ - $T_i$ , then  $(X, \tau)$  is  $\lambda$ - $D_i$ ,  $i = 0, 1, 2$ .
- (iii) If  $(X, \tau)$  is  $\lambda$ - $D_i$ , then it is  $\lambda$ - $D_{i-1}$ ,  $i = 1, 2$ .

**Theorem 3.2.** For a space  $(X, \tau)$  the following statements are true:

- (1)  $(X, \tau)$  is  $\lambda$ - $D_0$  if and only if  $(X, \tau)$  is  $\lambda$ - $T_0$ .
- (2)  $(X, \tau)$  is  $\lambda$ - $D_1$  if and only if,  $(X, \tau)$  is  $\lambda$ - $D_2$ .

*Proof.* The sufficiency for (1) and (2) follows from the Remark 3.1.

Necessity condition for (1). Let  $(X, \tau)$  be  $\lambda$ - $D_0$  so that for any distinct pair of points  $x$  and  $y$  of  $X$  at least one belongs to a  $\lambda$ -D set  $O$ . Therefore we choose  $x \in O$  and  $y \notin O$ . Suppose  $O = U \setminus V$  for which  $U \neq X$  and  $U$  and  $V$  are  $\lambda$ -open sets in  $X$ . This implies that  $x \in U$ . For the case that  $y \notin O$  we have



(i)  $y \notin U$ , (ii)  $y \in U$  and  $y \in V$ . For (i), the space  $X$  is  $\lambda$ - $T_0$  since  $x \in U$  and  $y \notin U$ . For (ii), the space  $X$  is also  $\lambda$ - $T_0$  since  $y \in V$  but  $x \notin V$ .

The necessity condition for (2). Suppose that  $X$  is  $\lambda$ - $D_1$ . It follows from the definition that for any distinct points  $x$  and  $y$  in  $X$  there exist  $\lambda$ - $D$  sets  $G$  and  $E$  such that  $G$  containing  $x$  but not  $y$  and  $E$  containing  $y$  but not  $x$ . Let  $G = U \setminus V$  and  $E = W \setminus D$ , where  $U, V, W$  and  $D$  are  $\lambda$ -open sets in  $X$ . By the fact that  $x \notin E$ , we have two cases, i.e. either  $x \notin W$  or both  $W$  and  $D$  contain  $x$ . If  $x \notin W$ , then from  $y \notin G$  either (i)  $y \notin U$  or (ii)  $y \in U$  and  $y \in V$ . If (i) is the case, then it follows from  $x \in U \setminus V$  that  $x \in U \setminus (V \cup W)$ , and also it follows from  $y \in W \setminus D$  that  $y \in (U \cup D)$ . Thus we have  $U \setminus (V \cup W)$  and  $W \setminus (U \cup D)$  which are disjoint. If (ii) is the case, it follows that  $x \in U \setminus V$  and  $y \in V$  since  $y \in U$  and  $y \in V$ . Therefore  $(U \setminus V) \cap V = \emptyset$ . If  $x \in W$  and  $x \in D$ , we have  $y \in W \setminus D$  and  $x \in D$ . Hence  $(W \setminus D) \cap D = \emptyset$ . This shows that  $X$  is  $\lambda$ - $D_2$ . □

**Theorem 3.3.** *If  $(X, \tau)$  is  $\lambda$ - $D_1$ , then it is  $\lambda$ - $T_0$ .*

*Proof.* Remark 3.1(iii) and Theorem 3.2. □

We give an example which shows that the converse of Theorem 3.3 is false.

**Example 3.4.** *Let  $X = \{a, b\}$  with topology  $\tau = \{\emptyset, \{a\}, X\}$ . Then  $(X, \tau)$  is  $\lambda$ - $T_0$ , but not  $\lambda$ - $D_1$  since there is not a  $\lambda$ - $D$ -set containing  $a$  but not  $b$ .*

**Example 3.5.** *Let  $X = \{a, b, c, d\}$  with topology  $\tau = \{\emptyset, \{c\}, \{b\}, \{b, c\}, \{b, c, d\}, X\}$ . Then we have that  $\{a\}, \{a, d\}, \{a, b, d\}$  and  $\{a, c, d\}$  are  $\lambda$ -open and  $(X, \tau)$  is a  $\lambda$ - $D_1$ , since  $\{a\}, \{b\} = \{a, b, d\} \setminus \{a, d\}, \{c\} = \{a, c, d\} \setminus \{a, d\}, \{d\} = \{a, d\} \setminus \{a\}$ . But  $(X, \tau)$  is not  $\lambda$ - $T_2$ .*

**Example 3.6.**

(1) *As a consequence of the Example 3.4, we obtain that  $(X, \tau)$  is  $\lambda$ - $T_0$ , but not  $\lambda$ - $T_1$ .*

(2) *As a consequence of the Example 3.5, we obtain that  $(X, \tau)$  is  $\lambda$ - $T_0$ , but not  $\lambda$ - $T_2$ .*

A subset  $B_x$  of a space  $X$  is said to be a  $\lambda$ -neighbourhood of a point  $x \in X$  if and only if there exists a  $\lambda$ -open set  $A$  such that  $x \in A \subset B_x$ .

**Definition 12.** *Let  $x$  be a point in a space  $X$ . If  $x$  does not have a  $\lambda$ -neighbourhood other than  $X$ , then we call  $x$  a  $\lambda$ -neat point. neighbourhood*

**Theorem 3.7.** *For a  $\lambda$ - $T_0$  space  $(X, \tau)$  the following are equivalent:*

- (1)  $(X, \tau)$  is  $\lambda$ - $D_1$ ;
- (2)  $(X, \tau)$  has no  $\lambda$ -neat point.

*Proof.* (1)  $\rightarrow$  (2) : If  $X$  is  $\lambda$ - $D_1$  then each point  $x \in X$  belongs to a  $\lambda$ - $D$ -set  $A = U \setminus V$ ; hence  $x \in U$ . Since  $U \neq X$ , thus  $x$  is not a  $\lambda$ -neat point.

(2)  $\rightarrow$  (1) : If  $X$  is  $\lambda$ - $T_0$ , then for each distinct pair of points  $x, y \in X$ , at least one of  $x, y$ , say  $x$  has a  $\lambda$ -neighbourhood  $U$  such that  $x \in U$  and  $y \notin U$ .

Hence  $U \neq X$  is a  $\lambda$ - $D$ -set. If  $X$  does not have a  $\lambda$ -neat point, then  $y$  is not a  $\lambda$ -neat point. So there exists a  $\lambda$ -neighbourhood  $V$  of  $y$  such that  $V \neq X$ . Now  $y \in V \setminus U$ ,  $x \notin V \setminus U$  and  $V \setminus U$  is a  $\lambda$ - $D$ -set. Therefore  $X$  is  $\lambda$ - $D_1$ .  $\square$

**Corollary 3.8.** *A  $\lambda$ - $T_0$  space  $X$  is not  $\lambda$ - $D_1$  if and only if there is a unique  $\lambda$ -neat point in  $X$ .*

*Proof.* We only prove the uniqueness of the  $\lambda$ -neat point. If  $x$  and  $y$  are two  $\lambda$ -neat points in  $X$ , then since  $X$  is  $\lambda$ - $T_0$ , at least one of  $x$  and  $y$ , say  $x$ , has a  $\lambda$ -neighborhood  $U$  such that  $x \in U$ ,  $y \notin U$ . Hence  $U \neq X$ . Therefore  $x$  is not a  $\lambda$ -neat point which is a contradiction.  $\square$

**Theorem 3.9.** *A space  $X$  is  $\lambda$ - $T_0$  if and only if for each pair of distinct points  $x, y$  of  $X$ ,  $Cl_\lambda(\{x\}) \neq Cl_\lambda(\{y\})$ .*

*Proof.* Sufficiency. Suppose that  $x, y \in X$ ,  $x \neq y$  and  $Cl_\lambda(\{x\}) \neq Cl_\lambda(\{y\})$ . Let  $z$  be a point of  $X$  such that  $z \in Cl_\lambda(\{x\})$  but  $z \notin Cl_\lambda(\{y\})$ . We claim that  $x \notin Cl_\lambda(\{y\})$ . For, if  $x \in Cl_\lambda(\{y\})$ , then  $Cl_\lambda(\{x\}) \subset Cl_\lambda(\{y\})$ . This contradicts the fact that  $z \notin Cl_\lambda(\{y\})$ . Consequently  $x$  belongs to the  $\lambda$ -open set  $[Cl_\lambda(\{y\})]^c$  to which  $y$  does not belong.

Necessity. Let  $X$  be a  $\lambda$ - $T_0$  space and  $x, y$  be any two distinct points of  $X$ . There exists a  $\lambda$ -open set  $G$  containing  $x$  or  $y$ , say  $x$  but not  $y$ . Then  $G^c$  is a  $\lambda$ -closed set which does not contain  $x$  but contains  $y$ . Since  $Cl_\lambda(\{y\})$  is the smallest  $\lambda$ -closed set containing  $y$  (Lemma 2.6),  $Cl_\lambda(\{y\}) \subset G^c$ , and so  $x \notin Cl_\lambda(\{y\})$ . Consequently  $Cl_\lambda(\{x\}) \neq Cl_\lambda(\{y\})$ .  $\square$

**Theorem 3.10.** *A space  $X$  is  $\lambda$ - $T_1$  if and only if the singletons are  $\lambda$ -closed sets.*

*Proof.* Suppose  $X$  is  $\lambda$ - $T_1$  and  $x$  is any point of  $X$ . Let  $y \in \{x\}^c$ . Then  $x \neq y$ . So there exists a  $\lambda$ -open set  $A_y$  such that  $y \in A_y$  but  $x \notin A_y$ . Consequently  $y \in A_y \subset \{x\}^c$  i.e.,  $\{x\}^c = \bigcup \{A_y / y \in \{x\}^c\}$  which is  $\lambda$ -open.

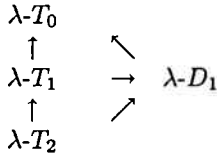
Conversely, let  $x, y \in X$  with  $x \neq y$ . Now  $x \neq y$  implies  $y \in \{x\}^c$ . Hence  $\{x\}^c$  is a  $\lambda$ -open set containing  $y$  but not  $x$ . Similarly  $\{y\}^c$  is a  $\lambda$ -open set containing  $x$  but not  $y$ . Accordingly  $X$  is a  $\lambda$ - $T_1$  space.  $\square$

**Theorem 3.11.** *A topological space  $X$  is  $\lambda$ - $T_1$  if and only if  $X$  is  $T_0$ .*

*Proof.* This is proved by Theorem 3.10 and [1][Theorem 2.5.]  $\square$

**Example 3.12.** *The Khalimsky line or the so-called digital line ([8], [9]) is the set of the integers,  $\mathbf{Z}$ , equipped with the topology  $\mathbf{K}$ , having  $\{\{2n-1, 2n, 2n+1\} : n \in \mathbf{Z}\}$  as a subbase. This space is of great importance in the study of applications of point-set topology to computer graphics. In the digital line  $(\mathbf{Z}, \mathbf{K})$ , every singleton is open or closed, that is, the digital line is  $T_0$ . Thus by Theorem 3.11, the digital line is  $\lambda$ - $T_1$  which is not  $T_1$ .*

**Remark 3.13.** *From Example 3.4, Example 3.5, Example 3.6 and Example 3.12 we have the following diagram:*



(1)  $T_1 \implies \lambda-T_1$  and  $T_2 \implies \lambda-T_2$ . The converses are not true:

**Example 3.14.** Let  $(X, \tau)$  be a topological space such that  $X = \{a, b, c\}$  and  $\tau = \{\emptyset, \{a\}, \{a, b\}, X\}$ . Then we have that

$$\lambda O(X, \tau) = \{\emptyset, \{a\}, \{c\}, \{a, b\}, \{a, c\}, \{b, c\}, X\}.$$

Therefore:

(i)  $(X, \tau)$  is  $\lambda-T_1$  but it is not  $T_1$ . (see also as another example the Khalimsky line i.e., the digital line which is given in Example 3.12).

(ii)  $(X, \tau)$  is  $\lambda-T_2$  but it is not  $T_2$ .

(2)  $T_0$  implies  $\lambda-T_0$  But the converse is not true as it is shown in the following example.

**Example 3.15.** Let  $X = \{a, b\}$  with topology  $\tau = \{\emptyset, \{a\}, X\}$ . Then  $(X, \tau)$  is  $\lambda-T_0$ . Observe that  $(X, \tau)$  is not  $T_0$ .

(3)  $\lambda-T_1$  implies  $\lambda-T_0$  and  $\lambda-T_2$  implies  $\lambda-T_0$ . The converses are not true (Example 3.6).

(4)  $\lambda-R_1$  implies  $\lambda-R_0$ . The converse is not true (Example 3.15).

(5)  $\lambda-T_1$  does not imply  $R_0$  and  $\lambda-T_0$  does not imply  $R_0$ . (Example 3.14).

(6)  $R_1$  implies  $R_0$  [3]. The converse is not true as it is shown by the following example.

**Example 3.16.** Let  $X = \{a, b\}$  with indiscrete topology  $\tau$ . Then  $(X, \tau)$  is  $R_0$  but it is not  $R_1$ .

(7) (i)  $\lambda-R_0 \not\rightleftharpoons R_0$  and (ii)  $\lambda-R_1 \not\rightleftharpoons R_1$  (Example 3.14).

(8) (i)  $T_{\frac{1}{2}}$  implies  $T_0$  which is equivalent with  $\lambda-T_1$  (see Theorem 3.11) and (ii)  $T_{\frac{1}{2}}$  implies  $\lambda-T_{\frac{1}{2}}$ . The converses are not true. For case (i), it is well known and for case (ii), it follows from the fact that every  $\lambda-T_1$  is  $\lambda-T_{\frac{1}{2}}$  (where a topological space is  $\lambda-T_{\frac{1}{2}}$  [2] if every singleton is  $\lambda$ -open or  $\lambda$ -closed).

(9)  $\lambda-T_1 \not\rightleftharpoons T_{\frac{1}{2}}$ . It is shown in the following example.

**Example 3.17.** [1][Example 3.2]] Let  $X$  be the set of non-negative integers with the topology whose open sets are those which contain 0 and have finite complement. This space is not  $T_{\frac{1}{2}}$ , but it is  $T_0$  is equivalent with  $\lambda-T_1$  (see Theorem 3.11). Therefore also  $\lambda-T_{\frac{1}{2}}$  does not imply  $T_{\frac{1}{2}}$ .

- (10)  $X$  is a  $T_{\frac{1}{4}}$ -space [1] if and only if every finite subset of  $X$  is  $\lambda$ -closed. We see that  $T_{\frac{1}{4}}$ -space is strictly placed between  $T_{\frac{1}{2}}$  and  $\lambda$ - $T_1$ . On the other hand, the space  $X = \{a, b, c\}$  with  $\tau = \{\emptyset, \{a\}, \{a, b\}, X\}$  is  $\lambda$ - $T_1$  but not  $T_{\frac{1}{4}}$ . Example 3.17 is an example of a space  $T_{\frac{1}{4}}$  which is not  $T_{\frac{1}{2}}$ .

In what follows, we refer the interested reader to [10] for the basic definitions and notations. Recall that a representation of a  $C^*$ -algebra  $\mathcal{A}$  consists of a Hilbert space  $\mathcal{H}$  and a  $*$ -morphism  $\pi : \mathcal{A} \rightarrow \mathcal{B}(\mathcal{H})$ , where  $\mathcal{B}(\mathcal{H})$  is the  $C^*$ -algebra of bounded operators on  $\mathcal{H}$ . A subspace  $\mathcal{I}$  of a  $C^*$ -algebra  $\mathcal{A}$  is called a primitive ideal if  $\mathcal{I} = \ker(\pi)$  for some irreducible representation  $(\mathcal{H}, \pi)$  of  $\mathcal{A}$ . The set of all primitive ideals of a  $C^*$ -algebra  $\mathcal{A}$  plays a very important role in noncommutative spaces and its relation to particle physics. We denote this set by  $\text{Prim } \mathcal{A}$ . As Landi [10] mentions, for a noncommutative  $C^*$ -algebra, there is more than one candidate for the analogue of the topological space  $X$ :

1. The structure space of  $\mathcal{A}$  or the space of all unitary equivalence classes of irreducible  $*$ -representations and
2. The primitive spectrum of  $\mathcal{A}$  or the space of kernels of irreducible  $*$ -representations which is denoted by  $\text{Prim } \mathcal{A}$ . Observe that any element of  $\text{Prim } \mathcal{A}$  is a two-sided  $*$ -ideal of  $\mathcal{A}$ .

It should be noticed that for a commutative  $C^*$ -algebra, 1 and 2 are the same but this is not true for a general  $C^*$ -algebra  $\mathcal{A}$ . Natural topologies can be defined on spaces of 1 and 2. But here we are interested in the Jacobsen (or hull-kernel) topology defined on  $\text{Prim } \mathcal{A}$  by means of closure operators. The interested reader may refer to [4] for basic properties of  $\text{Prim } \mathcal{A}$ . It follows from Theorem 3.11 that  $\text{Prim } \mathcal{A}$  is also a  $\lambda$ - $T_1$ -space. Jafari [7] has shown that  $T_1$ -spaces are precisely those which are both  $R_0$  and  $\lambda$ - $T_1$ .

**Theorem 3.18.** *A space  $X$  is  $\lambda$ - $T_2$  if and only if the intersection of all  $\lambda$ -closed  $\lambda$ -neighborhoods of each point of the space is reduced to that point.*

*Proof.* Let  $X$  be  $\lambda$ - $T_2$  and  $x \in X$ . Then for each  $y \in X$ , distinct from  $x$ , there exist  $\lambda$ -open sets  $G$  and  $H$  such that  $x \in G$ ,  $y \in H$  and  $G \cap H = \emptyset$ . Since  $x \in G \subset H^c$ , then  $H^c$  is a  $\lambda$ -closed  $\lambda$ -neighborhood of  $x$  to which  $y$  does not belong. Consequently, the intersection of all  $\lambda$ -closed  $\lambda$ -neighborhood of  $x$  is reduced to  $\{x\}$ .

Conversely, let  $x, y \in X$  and  $x \neq y$ . Then by hypothesis, there exists a  $\lambda$ -closed  $\lambda$ -neighbourhood  $U$  of  $x$  such that  $y \notin U$ . Now there is a  $\lambda$ -open set  $G$  such that  $x \in G \subset U$ . Thus  $G$  and  $U^c$  are disjoint  $\lambda$ -open sets containing  $x$  and  $y$ , respectively. Hence  $X$  is  $\lambda$ - $T_2$ .  $\square$

**Definition 13.** *A space  $(X, \tau)$  will be termed  $\lambda$ -symmetric if for any  $x$  and  $y$  in  $X$ ,  $x \in Cl_{\lambda}(\{y\})$  implies  $y \in Cl_{\lambda}(\{x\})$ .*

**Definition 14.** *A subset  $A$  of a space  $(X, \tau)$  is called a  $\lambda$ -generalized closed set (briefly  $\lambda$ -g-closed) if  $Cl_{\lambda}(A) \subset U$  whenever  $A \subset U$  and  $U$  is  $\lambda$ -open in  $(X, \tau)$ .*

**Lemma 3.19.** *Every  $\lambda$ -closed set is  $\lambda$ -g-closed.*

**Example 3.20.** *In Example 3.6, if  $A = \{a\}$ , then  $A$  is a  $\lambda$ -g-closed set, but it is not a  $\lambda$ -closed set (hence it is not a closed set).*

**Theorem 3.21.** *Let  $(X, \tau)$  be a space. Then,*

- (i)  $(X, \tau)$  is  $\lambda$ -symmetric if and only if  $\{x\}$  is  $\lambda$ -g-closed for each  $x$  in  $X$ .
- (ii) If  $(X, \tau)$  is a  $\lambda$ - $T_1$  space, then  $(X, \tau)$  is  $\lambda$ -symmetric.
- (iii)  $(X, \tau)$  is  $\lambda$ -symmetric and  $\lambda$ - $T_0$  if and only if  $(X, \tau)$  is  $\lambda$ - $T_1$ .

*Proof.* (i) Sufficiency. Suppose  $x \in Cl_\lambda(\{y\})$ , but  $y \notin Cl_\lambda(\{x\})$ . Then  $\{y\} \subset [Cl_\lambda(\{x\})]^c$  and thus  $Cl_\lambda(\{y\}) \subset [Cl_\lambda(\{x\})]^c$ . Then  $x \in [Cl_\lambda(\{x\})]^c$ , a contradiction.

Necessity. Suppose  $\{x\} \subset E \in \lambda O(X, \tau) = \{B \subset X \mid B \text{ is } \lambda\text{-open}\}$ , but  $Cl_\lambda(\{x\}) \not\subseteq E$ . Then  $Cl_\lambda(\{x\}) \cap E^c \neq \emptyset$ ; take  $y \in Cl_\lambda(\{x\}) \cap E^c$ . Therefore  $x \in Cl_\lambda(\{y\}) \subset E^c$  and  $x \notin E$ , a contradiction.

(ii) In a  $\lambda$ - $T_1$  space, singleton sets are  $\lambda$ -closed (Theorem 3.10) and therefore  $\lambda$ -g-closed (Lemma 3.19). By (i), the space is  $\lambda$ -symmetric.

(iii) By (ii) and Remark 3.1(i) it suffices to prove only the necessity condition. Let  $x \neq y$ . By  $\lambda$ - $T_0$ , we may assume that  $x \in E \subset \{y\}^c$  for some  $E \in \lambda O(X, \tau)$ . Then  $x \notin Cl_\lambda(\{y\})$  and hence  $y \notin Cl_\lambda(\{x\})$ . There exists a  $F \in \lambda O(X, \tau)$  such that  $y \in F \subset \{x\}^c$  and thus  $(X, \tau)$  is a  $\lambda$ - $T_1$  space. ✓

**Theorem 3.22.** *Let  $(X, \tau)$  be a  $\lambda$ -symmetric space. Then the following are equivalent.*

- (i)  $(X, \tau)$  is  $\lambda$ - $T_0$ ,
- (ii)  $(X, \tau)$  is  $\lambda$ - $D_1$ ,
- (iii)  $(X, \tau)$  is  $\lambda$ - $T_1$ .

*Proof.* (i)  $\rightarrow$  (iii) : Theorem 3.21.

(iii)  $\rightarrow$  (ii)  $\rightarrow$  (i) : Remark 3.1 and Theorem 3.3. ✓

A function  $f : (X, \tau) \rightarrow (Y, \sigma)$  is called  $\lambda$ -irresolute if  $f^{-1}(V)$  is  $\lambda$ -open in  $(X, \tau)$  for every  $\lambda$ -open set  $V$  of  $(Y, \sigma)$ .

**Example 3.23.** *Let  $(X, \tau)$  be as Example 3.14 and  $f : (X, \tau) \rightarrow (X, \tau)$  such that  $f(a) = c$ ,  $f(b) = c$  and  $f(a) = a$ . Then  $f$  is  $\lambda$ -irresolute, but it is not irresolute.*

**Example 3.24** ([1]). *Consider the classical Dirichlet function  $f : \mathbb{R} \rightarrow \mathbb{R}$ , where  $\mathbb{R}$  is the real line with the usual topology:*

$$f(x) = \begin{cases} 1 & \text{if } x \text{ is rational} \\ 0 & \text{if } x \text{ is otherwise} \end{cases}$$

*Therefore  $f$  is  $\lambda$ -continuous, but it is not continuous.*

**Theorem 3.25.** *If  $f : (X, \tau) \rightarrow (Y, \sigma)$  is a  $\lambda$ -irresolute surjective function and  $S$  is a  $\lambda$ - $D$ -set in  $Y$ , then  $f^{-1}(A)$  is a  $\lambda$ - $D$ -set in  $X$ .*

*Proof.* Let  $A$  be a  $\lambda$ - $D$ -set in  $Y$ . Then there are  $\lambda$ -open sets  $U$  and  $V$  in  $Y$  such that  $A = U \setminus V$  and  $U \neq Y$ . By the  $\lambda$ -irresoluteness of  $f$ ,  $f^{-1}(U)$  and  $f^{-1}(V)$  are  $\lambda$ -open in  $X$ . Since  $U \neq Y$ , we have  $f^{-1}(U) \neq X$ . Hence  $f^{-1}(A) = f^{-1}(U) \setminus f^{-1}(V)$  is a  $\lambda$ - $D$ -set.  $\square$

**Theorem 3.26.** *If  $(Y, \sigma)$  is  $\lambda$ - $D_1$  and  $f : (X, \tau) \rightarrow (Y, \sigma)$  is  $\lambda$ -irresolute and bijective, then  $(X, \tau)$  is  $\lambda$ - $D_1$ .*

*Proof.* Suppose that  $Y$  is a  $\lambda$ - $D_1$  space. Let  $x$  and  $y$  be any pair of distinct points in  $X$ . Since  $f$  is injective and  $Y$  is  $\lambda$ - $D_1$ , there exist  $\lambda$ - $D$ -sets  $A_x$  and  $B_y$  of  $Y$  containing  $f(x)$  and  $f(y)$  respectively, such that  $f(y) \notin A_x$  and  $f(x) \notin B_y$ . By Theorem 3.25,  $f^{-1}(A_x)$  and  $f^{-1}(B_y)$  are  $\lambda$ - $D$ -sets in  $X$  containing  $x$  and  $y$ , respectively. This implies that  $X$  is a  $\lambda$ - $D_1$  space.  $\square$

We now prove another characterization of  $\lambda$ - $D_1$  spaces.

**Theorem 3.27.** *A space  $X$  is  $\lambda$ - $D_1$  if and only if for each pair of distinct points  $x$  and  $y$  in  $X$ , there exists a  $\lambda$ -irresolute surjective function  $f$  of  $X$  onto a  $\lambda$ - $D_1$  space  $Y$  such that  $f(x) \neq f(y)$ .*

*Proof.* Necessity. For every pair of distinct points of  $X$ , it suffices to take the identity function on  $X$ .

Sufficiency. Let  $x$  and  $y$  be any pair of distinct points in  $X$ . By hypothesis, there exists a  $\lambda$ -irresolute, surjective function  $f$  of a space  $X$  onto a  $\lambda$ - $D_1$  space  $Y$  such that  $f(x) \neq f(y)$ . Therefore, there exist disjoint  $\lambda$ - $D$ -sets  $A_x$  and  $B_y$  in  $Y$  such that  $f(x) \in A_x$  and  $f(y) \in B_y$ . Since  $f$  is  $\lambda$ -irresolute and surjective, by Theorem 3.25,  $f^{-1}(A_x)$  and  $f^{-1}(B_y)$  are disjoint  $\lambda$ - $D$ -sets in  $X$  containing  $x$  and  $y$ , respectively. Hence by Theorem 3.2(2),  $X$  is  $\lambda$ - $D_1$  space.  $\square$

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